

# Non-Ergodic Site Response in Seismic Hazard Analysis

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# Acknowledgements

Co-Author:

Kioumars Afshari, UCLA

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Kevin Milner, Christine Goulet, SCEC

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EERI, SSA:

Sponsorship of Joyner Lecture

# Objectives

Understand differences between non-ergodic and ergodic site response

Present framework for developing site-specific GMPE for use in ground motion hazard analysis

Effects on hazard

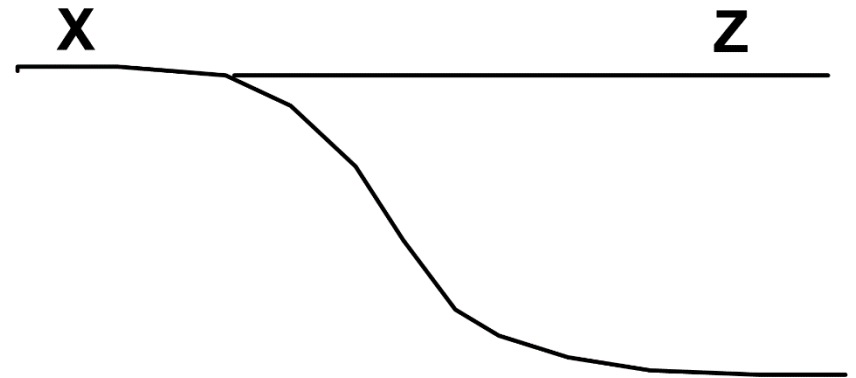
Takes some effort, but tools available ... and worth it

# Outline

- Ergodic site amplification
- Non-ergodic (location-specific) site amplification
- Implementation in PSHA
- Summary

# Notation

- IM = intensity measure
- $X$  = Reference site IM
- $Z$  = soil site IM
- $Y = Z / X$   
(site amplification)



# Ergodic Models

- *Ergodic*: Ground motions evaluated from diverse (global) data set
- Examples:
  - $V_{s30}$ - and depth-dependent site terms in GMPEs
  - Site amplification coefficients in building codes

# GMPE

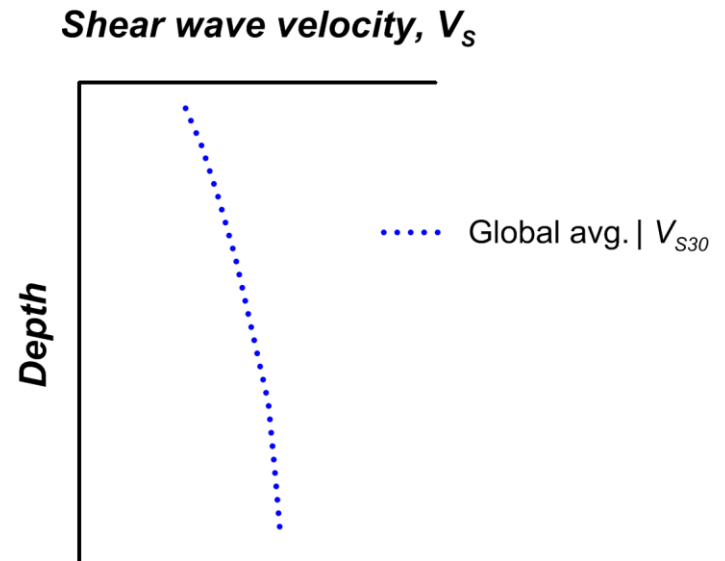
$$\ln Z = \underbrace{F_E + F_P}_{\text{Ergodic source \& path}} + \underbrace{F_S}_{\text{Ergodic effect of site}} + \varepsilon_n \sigma_{\ln Z}$$

Ergodic source & path

$F_S$ : ergodic effect of site

Two components:

$$F_S = F_{lin} + F_{nl}$$



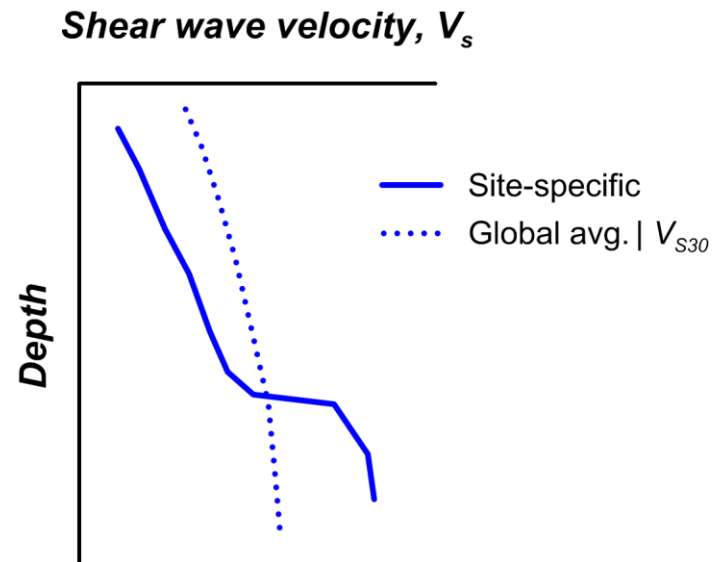
# GMPE

$$\ln Z = \underbrace{F_E + F_P}_{\text{Ergodic source \& path}} + \underbrace{F_S}_{\text{Site-specific}} + \varepsilon_n \sigma_{\ln Z}$$

Ergodic source & path

$F_S$ : ergodic effect of site

Actual for site  $j$ :  $F_S + \eta_{sj}$





## **GMPE**

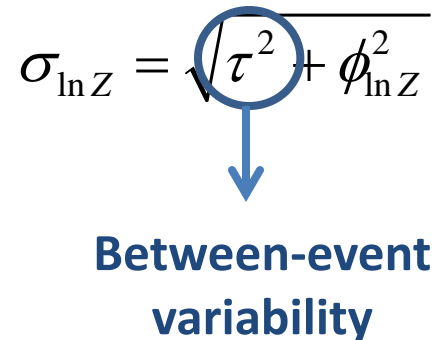
$$\ln Z = F_E + F_P + F_S + \varepsilon_n \sigma_{\ln Z}$$

Ergodic source & path

$F_S$ : ergodic effect of site

Actual for site  $j$ :  $F_S + \eta_{sj}$

$\sigma_{\ln Z}$ : ergodic total standard deviation

$$\sigma_{\ln Z} = \sqrt{\tau^2 + \phi_{\ln Z}^2}$$


The diagram shows the equation  $\sigma_{\ln Z} = \sqrt{\tau^2 + \phi_{\ln Z}^2}$ . A blue circle highlights the term  $\tau^2$  inside the square root. A blue arrow points downwards from this circle to the text "Between-event variability".

**Between-event  
variability**

# GMPE

$$\ln Z = F_E + F_P + F_S + \varepsilon_n \sigma_{\ln Z}$$


Ergodic source & path

$F_S$ : ergodic effect of site

Actual for site  $j$ :  $F_S + \eta_{sj}$

$\sigma_{\ln Z}$ : ergodic total standard deviation

Modified from Al Atik et al. (2010)

$$\sigma_{\ln Z} = \sqrt{\tau^2 + \phi_{\ln Z}^2}$$


**Within-event  
variability**

$$\phi_{P2P}^2 + \phi_{S2S}^2 + \phi_{\ln Y}^2$$

# Importance of $\sigma$

Consider example site

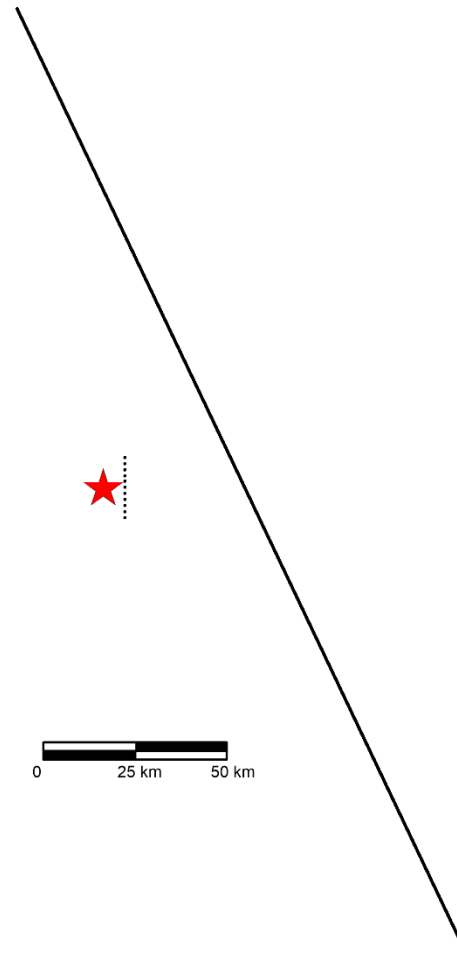


Figure: P. Zimmaro.

# Importance of $\sigma$

Consider example site

Hazard with as-published  
ergodic  $\sigma$  & sensitivity

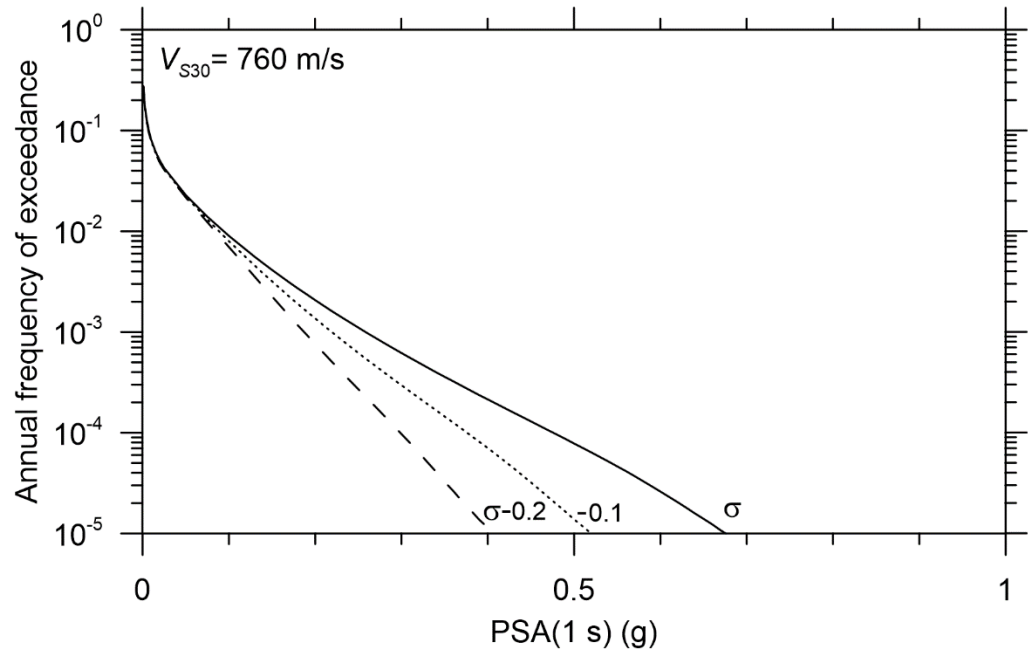


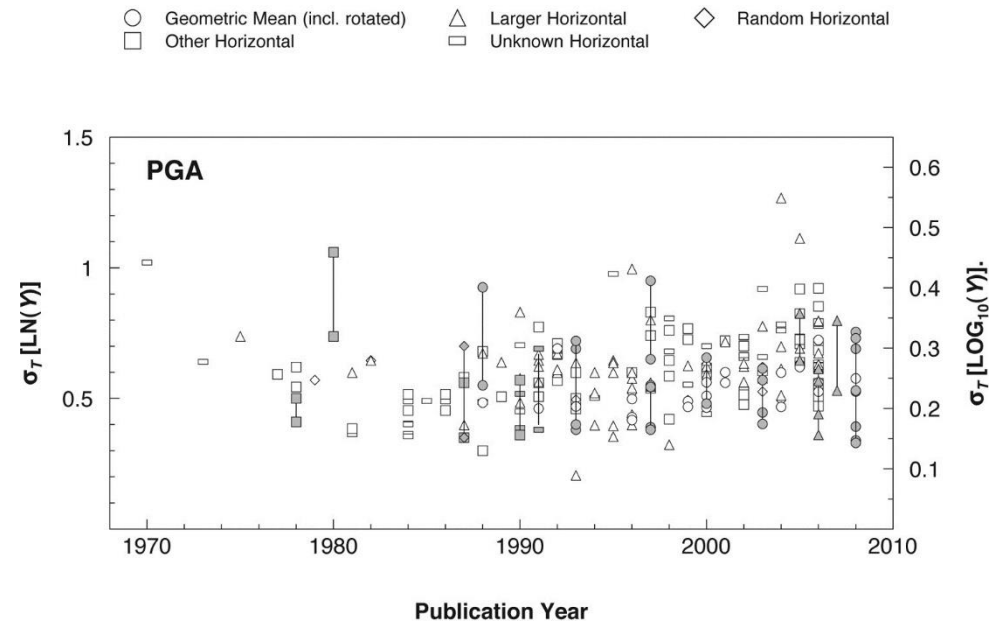
Figure: P. Zimmaro. Similar to  
Bommer and Abrahamson, 2006

# Importance of $\sigma$

Consider example site

Hazard with as-published  
ergodic  $\sigma$  & sensitivity

Ergodic  $\sigma$  difficult to reduce  
as GMPEs evolve...



After Strasser et al., 2009

# Outline

- Ergodic site amplification
- **Non-ergodic (location-specific) site amplification**
- Implementation in PSHA
- Summary

# Non-Ergodic Site Amplification

- *Non-Ergodic*: Amplification is site-specific
  - Bias removal
  - Reduced dispersion
- Evaluation from:
  - On-site recordings
  - Geotechnical simulations
- Site response model:  $\mu_{\ln Y}$ ,  $\phi_{\ln Z}$

## ***Dispersion reduction***

Recall  $\phi_{\ln Z}^2 = \phi_{P2P}^2 + \phi_{S2S}^2 + \phi_{\ln Y}^2$

$\phi_{\ln Z}$  from GMPE

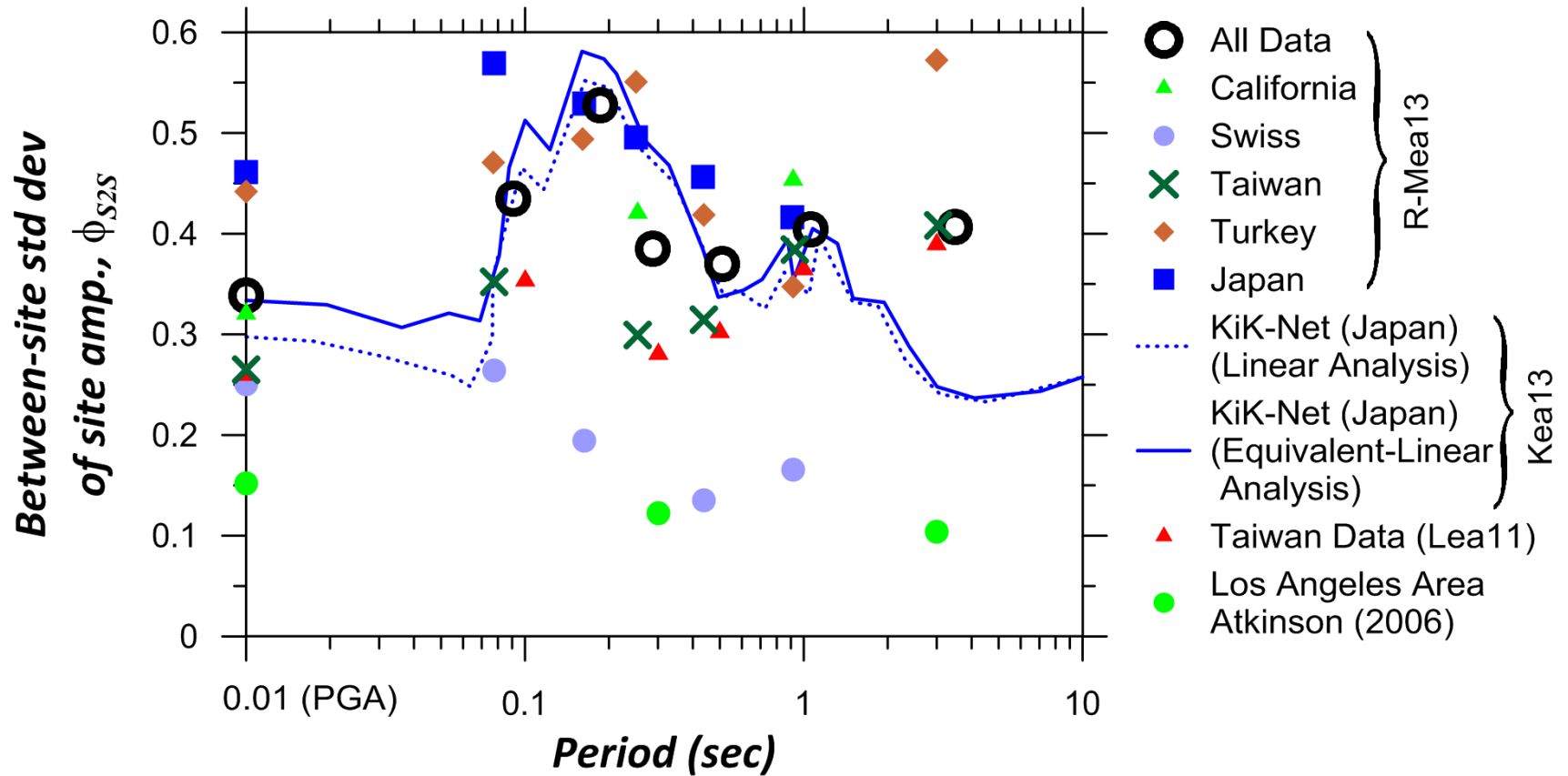
If site effect non-ergodic, can remove S2S-component:

Approach 1: use  $\approx \phi_{\ln Z}^2 - \phi_{S2S}^2$

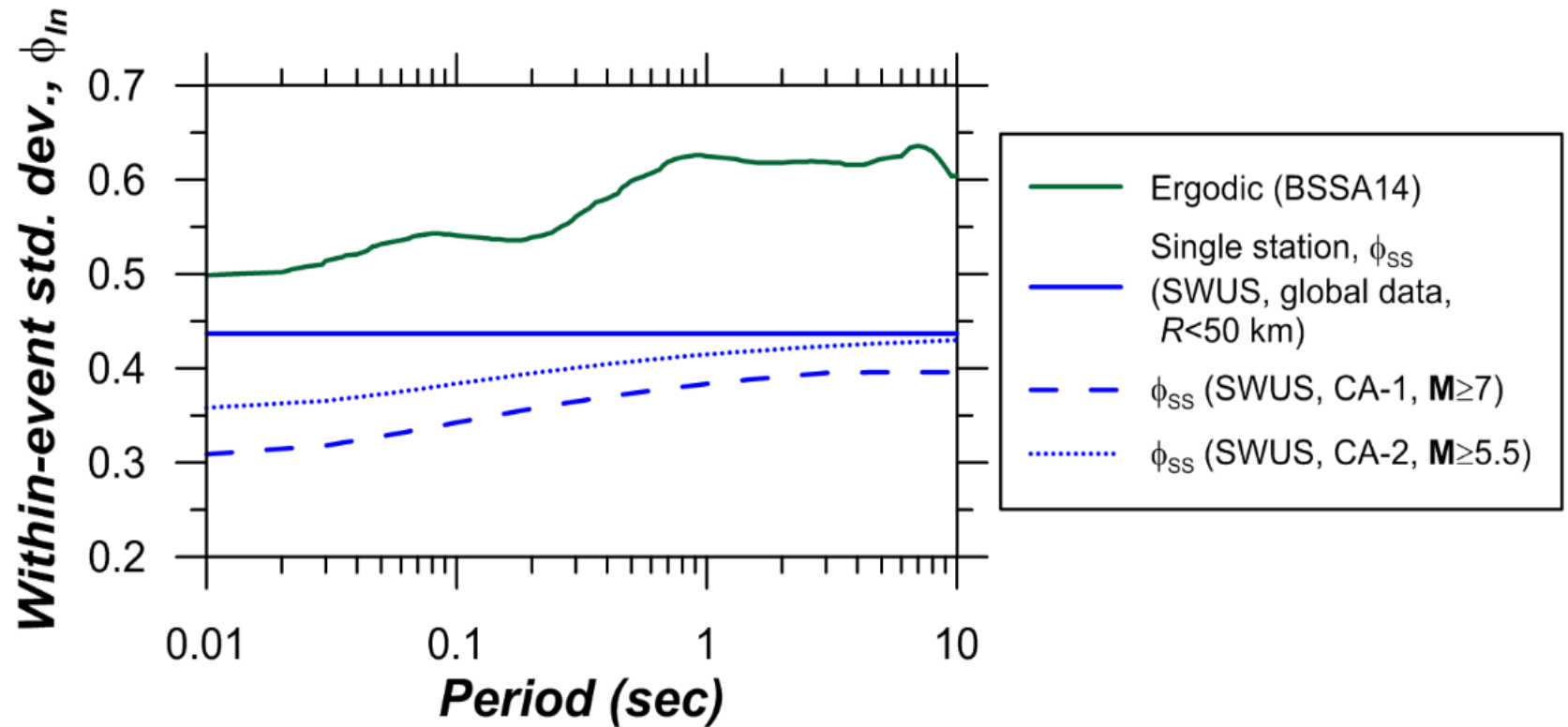
Approach 2: replace  $\phi_{P2P}^2 + \phi_{S2S}^2$  with  $\phi_{SS}^2$



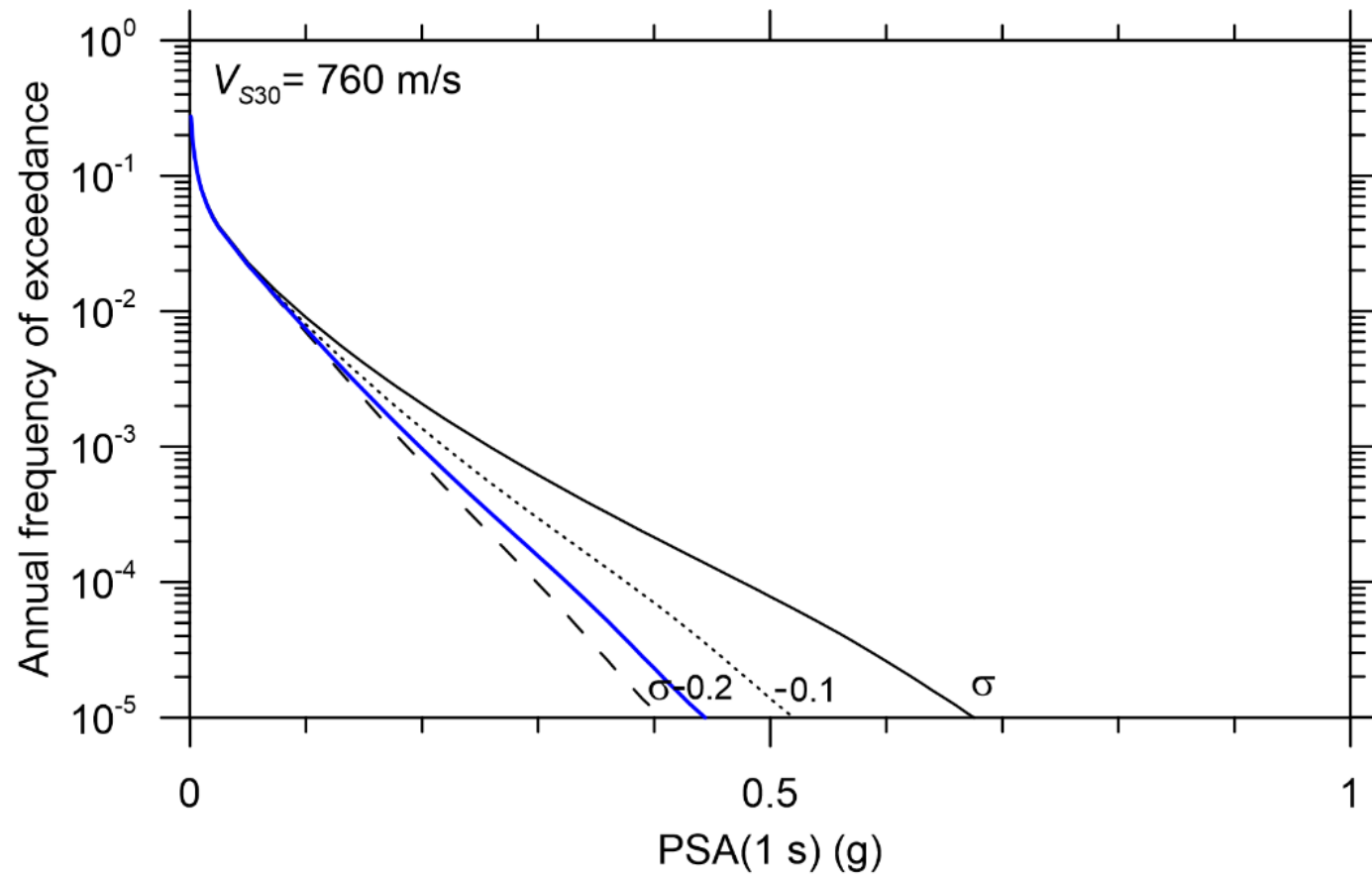
# Approach 1



## Approach 2



GMPE (ergodic) vs single-station ( $\phi_{ss}$ ) (GeoPentech, 2015)



# *Evaluation from Recordings*

Install sensors at Site  $j$

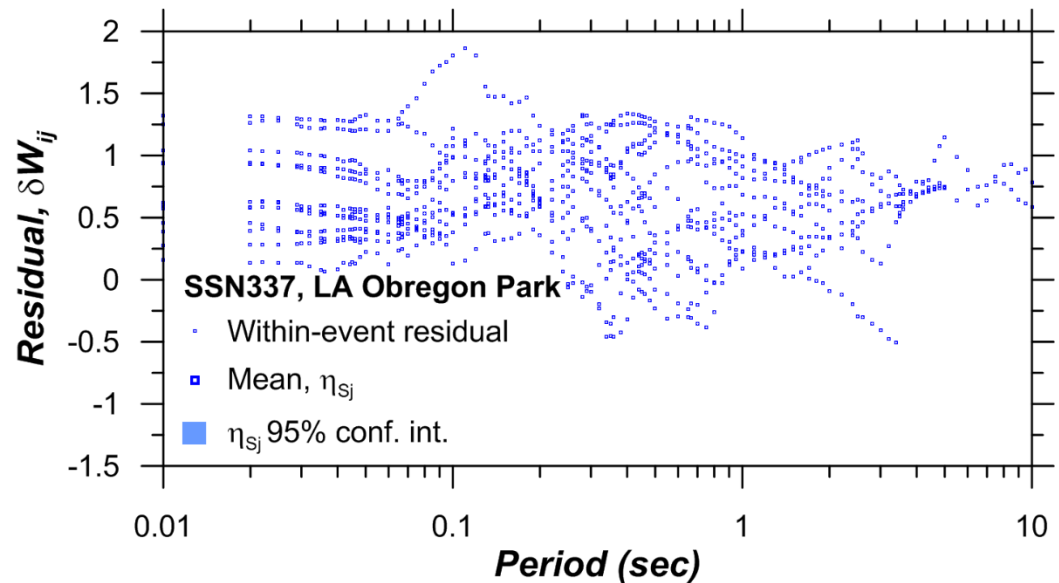
Record eqks in **M**-R  
range of GMPE (Site  $j$   
and others)

Compute residuals:

$$R_{ij} = \ln z_{ij} - \mu_{\ln Z, ij}$$

Partition residuals:

$$R_{ij} = \eta_{Ei} + \delta W_{ij}$$



# Evaluation from Recordings

Install sensors at Site  $j$

Record eqks in **M**-R  
range of GMPE (Site  $j$   
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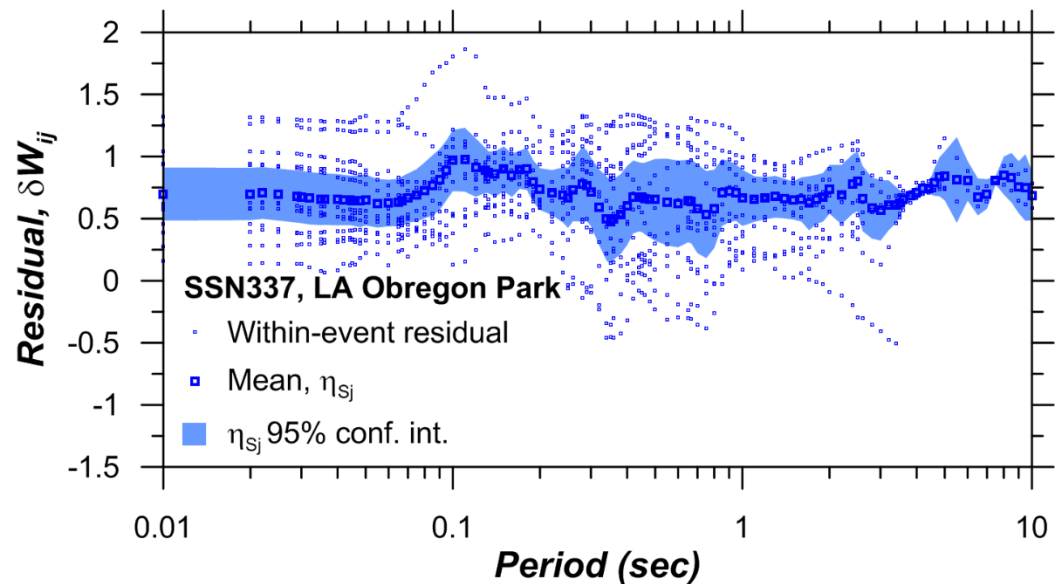
Compute residuals:

$$R_{ij} = \ln z_{ij} - \mu_{\ln Z, ij}$$

Partition residuals:

$$R_{ij} = \eta_{Ei} + \delta W_{ij}$$

Mean of  $\delta W_{ij}$  is  $\sim \eta_{Sj}$



# Evaluation from Recordings

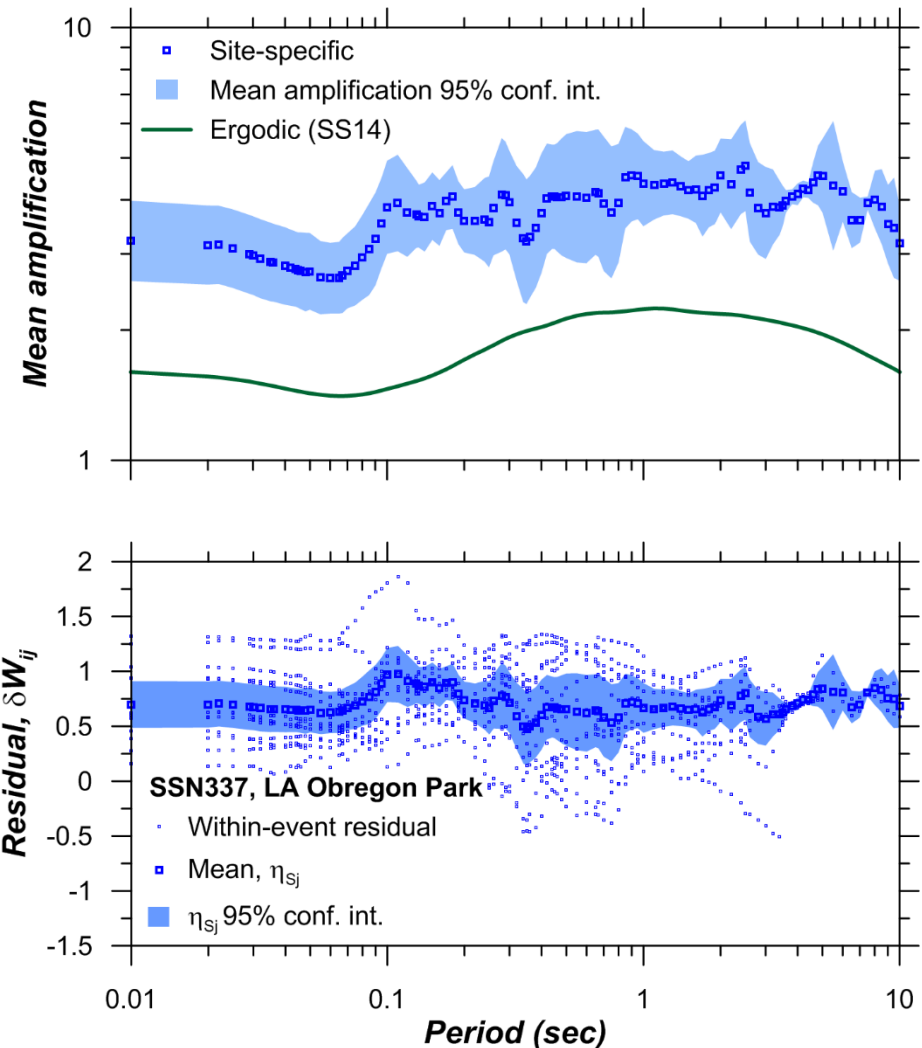
Mean linear site response:

$$\frac{F_{lin} + \eta_{sj}}{\text{Ergodic linear site term}}$$

$F_{nl}$  term can be added from simulations

Adjusts mean ground motion

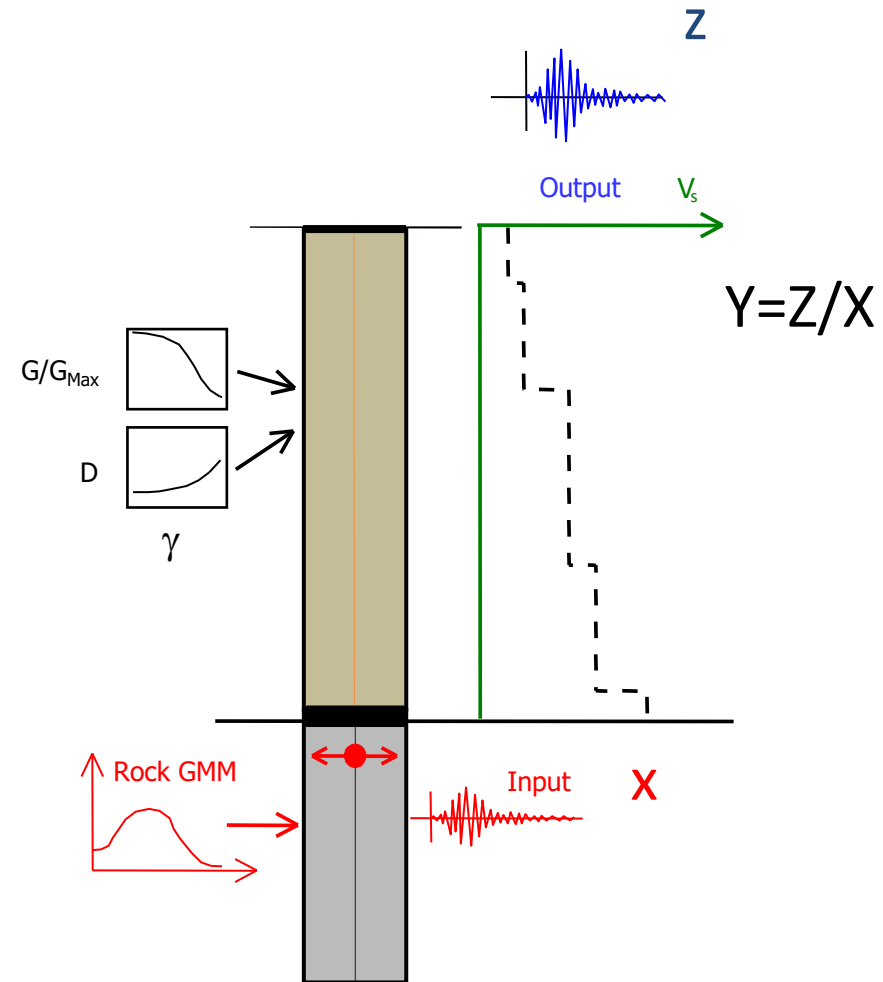
$$\mu_{\ln Z}$$



# *Evaluation from Simulations*

## Geotechnical 1D GRA

What is simulated, what is not.



# ***Evaluation from Simulations***

## **Geotechnical 1D GRA**

What is simulated, what is not.

Use range of input motions,  $X$ .  
For each, compute  $Y=Z/X$

(Detailed procedures in 2014  
PEER report)

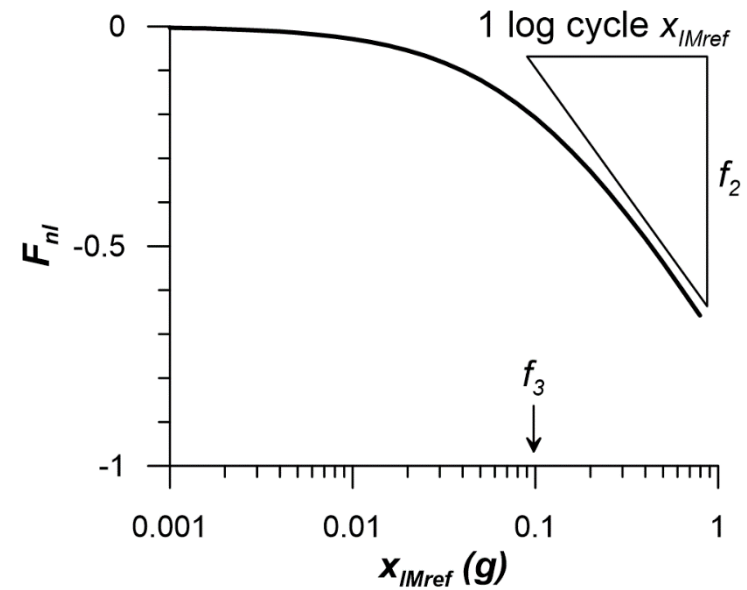
Limited effectiveness for many  
sites (e.g., Thompson et al. 2012)



# Site Response Model

Site-specific amplification  
function

$$\mu_{\ln Y} = \underbrace{f_1}_{F_{lin}} + \underbrace{f_2 \ln \left( \frac{x_{IMref} + f_3}{f_3} \right)}_{F_{nl}}$$

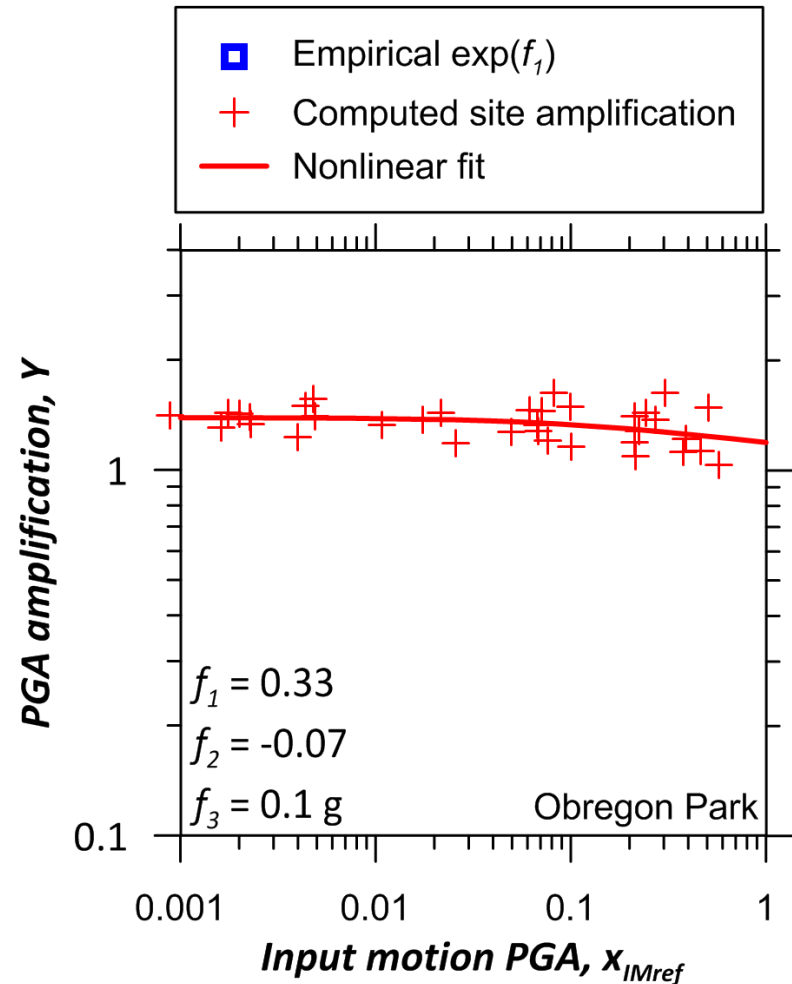


# Site Response Model

## Site-specific amplification function

Fit GRA results

Approximate fits possible if fewer runs



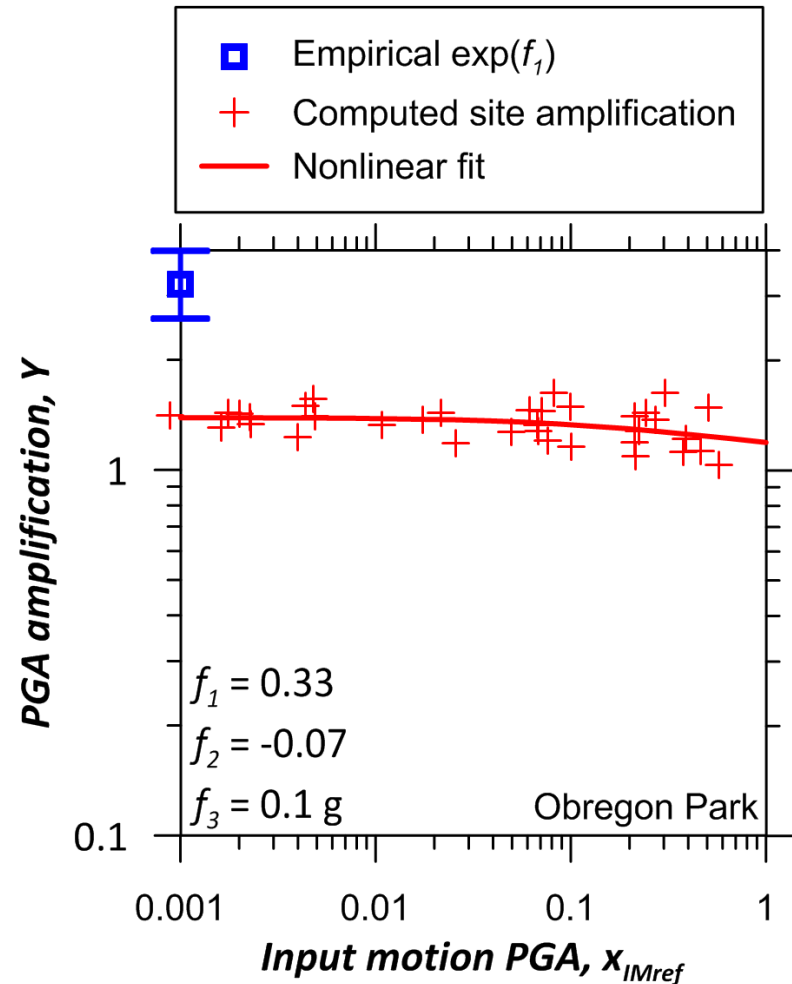
# Site Response Model

## Site-specific amplification function

Fit GRA results

Approximate fits possible if fewer runs

As available, note empirical amplification



# Site Response Model

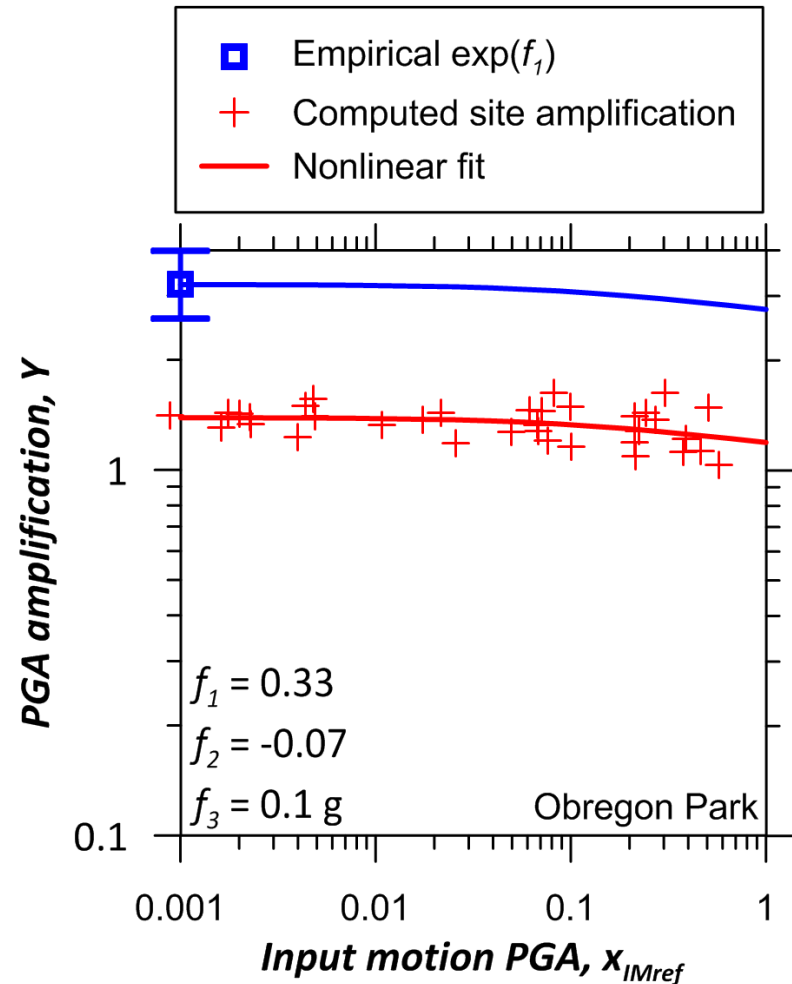
## Site-specific amplification function

Fit GRA results

Approximate fits possible if fewer runs

As available, note empirical amplification

Shift to match empirical for weak motion (semi-empirical approach)



# Site Response Model

Site-specific amplification  
function

Standard deviation term

$\phi_{\ln Z}$  reduced from  $\phi_{\ln X}$  due to:

- Nonlinearity

$$\mu_{\ln Y} = f_1 + f_2 \ln \left( \frac{x_{IMref} + f_3}{f_3} \right)$$

$$\phi_{\ln Z} = \sqrt{\left( \frac{f_2 x}{x + f_3} + 1 \right)^2} \left( \phi_{\ln X}^2 - F \phi_{S2S}^2 \right) + \phi_{\ln Y}^2$$

# Site Response Model

Site-specific amplification  
function

Standard deviation term

$\phi_{\ln Z}$  reduced from  $\phi_{\ln X}$  due to:

- Nonlinearity
- Non-ergodic  $\phi_{\ln}$

$$\mu_{\ln Y} = f_1 + f_2 \ln \left( \frac{x_{IMref} + f_3}{f_3} \right)$$

$$\phi_{\ln Z} = \sqrt{\left( \frac{f_2 x}{x + f_3} + 1 \right)^2 \left( \phi_{\ln X}^2 - F \phi_{S2S}^2 \right) + \phi_{\ln Y}^2}$$

**Approach 1**

# Site Response Model

Site-specific amplification  
function

Standard deviation term

$\phi_{\ln Z}$  reduced from  $\phi_{\ln X}$  due to:

- Nonlinearity
- Non-ergodic  $\phi_{\ln}$

$$\mu_{\ln Y} = f_1 + f_2 \ln \left( \frac{x_{IMref} + f_3}{f_3} \right)$$

$$\phi_{\ln Z} = \sqrt{\left( \frac{f_2 x}{x + f_3} + 1 \right)^2 \phi_{SS}^2 + \phi_{\ln Y}^2}$$

**Approach 2**

# Site Response Model

Site-specific amplification function

Standard deviation term

$\phi_{\ln Z}$  reduced from  $\phi_{\ln X}$  due to:

- Nonlinearity
- Non-ergodic  $\phi_{\ln}$

Include uncertainty in site amplification,  $\phi_{\ln Y} \approx 0.3$

$$\mu_{\ln Y} = f_1 + f_2 \ln \left( \frac{x_{IMref} + f_3}{f_3} \right)$$

$$\phi_{\ln Z} = \sqrt{\left( \frac{f_2 x}{x + f_3} + 1 \right)^2 \left( \phi_{\ln X}^2 - F \phi_{S2S}^2 \right) + \phi_{\ln Y}^2}$$



# ***Site Response Model***

Site-specific amplification  
function

Standard deviation term

**Epistemic uncertainty**

Should consider center & range of possible:

- Mean amplification functions
- $\phi_{lnZ}$  models

# Outline

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- Non-ergodic (location-specific) site amplification
- **Implementation in PSHA**
- Summary

# Hybrid

term from Cramer, 2003, and others

For any given probability,  $P$ :  $\ln(z) = \ln(\underbrace{\bar{Y}}_{x_{IMref}}) + \ln(\underbrace{x})$

*Mean site amplification  
given  $x$  from hazard curve*

*Read from  
hazard curve*

Dominant approach in practice (basis for building code ground motions)

# Convolution

Bazzurro and Cornell, 2004

Given: (1) Hazard curve for reference condition

$$P(X > x | \Delta t)$$

(2) Site amplification function:  $\mu_{\ln Y} = f(x_{IMref}) \phi_{\ln Y}$

$$P(Z > z | \Delta t) = \int_0^{\infty} \underbrace{P\left(Y > \frac{z}{x} | x_{IMref}\right)}_{\text{Simple probability operation given PDF for } Y} \underbrace{f_X(x)}_{\text{Abs. value of slope of hazard curve}} dx$$

*Simple probability  
operation given PDF for Y*

*Abs. value of slope  
of hazard curve*

Advantage relative to hybrid: uncertainty in  $Y$  considered

## ***Hybrid & Convolution - Summary***

### Advantages:

- Simple to implement. Only requires rock PSHA and amplification model.

### Drawbacks:

- PSHA based on  $\sigma_{\ln X}$  not  $\sigma_{\ln Z}$
- No allowance for non-ergodic standard deviation
- Controlling sources and epsilons based on rock GMPE
- Nonlinearity driven by X hazard ( $\varepsilon_X > 0$ ).

## ***Modify GMPE in hazard integral***

- Mean:  $\mu_{\ln Z} = \mu_{\ln X} + \mu_{\ln Y} \mid x_{IMref}$
- Adjusted  $\phi_{\ln Z}$

By default,  $x_{IMref}$  taken as mean value ( $\varepsilon = 0$ )

Pending technical issue: correlation of  $z$  and  $x_{IMref}$   
(unknown presently)

Consider epistemic uncertainties using logic trees –  
high uncertainty sites should have wider bounds

# OpenSHA Implementation



*Non-ergodic site response GMPE* can be selected as 'intensity measure relation'

Select GMPE for reference condition and its  $V_{s30}$

$V_{s30}$  and depth parameters for site

Coefficients entered for mean and st dev site model for range of periods.

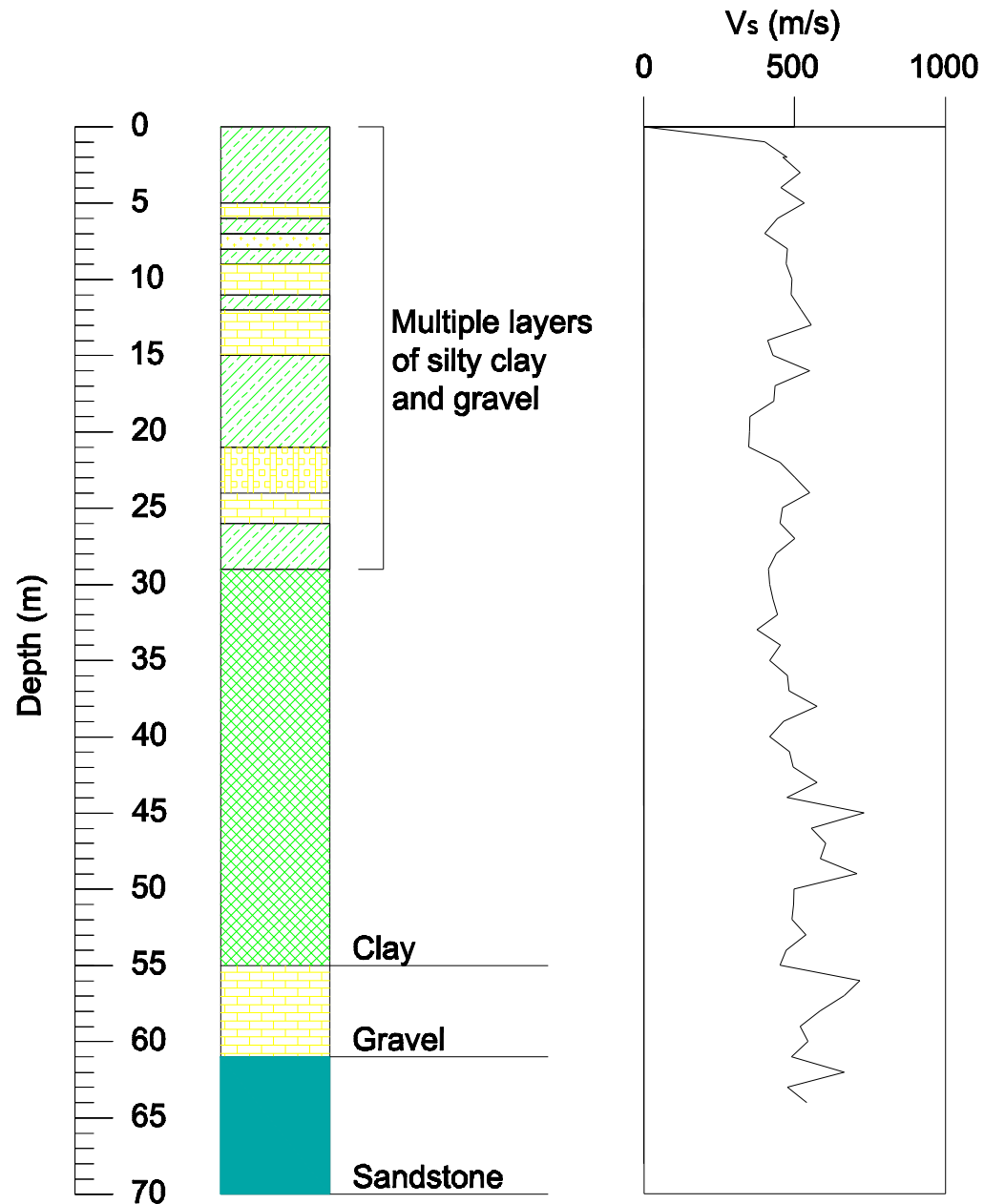
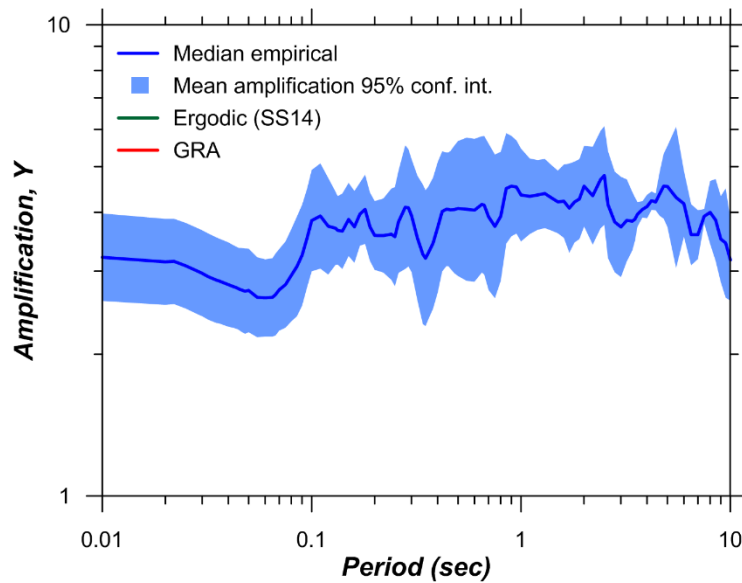
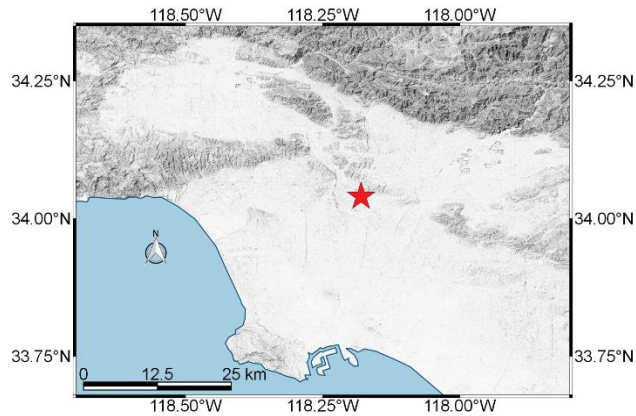
Fitted interpolation between periods with specified coefficients

Option to adjust to ergodic model at long periods.

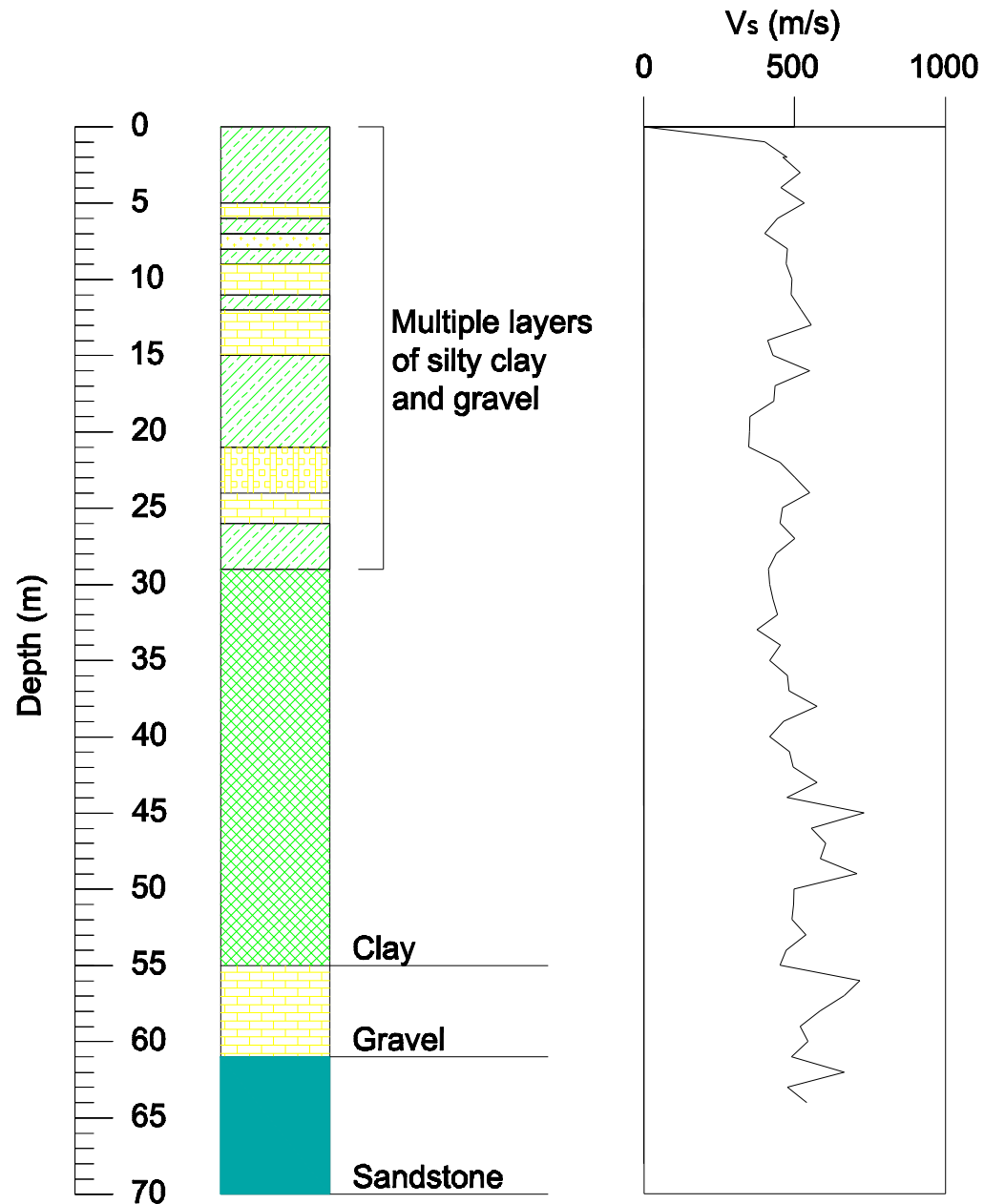
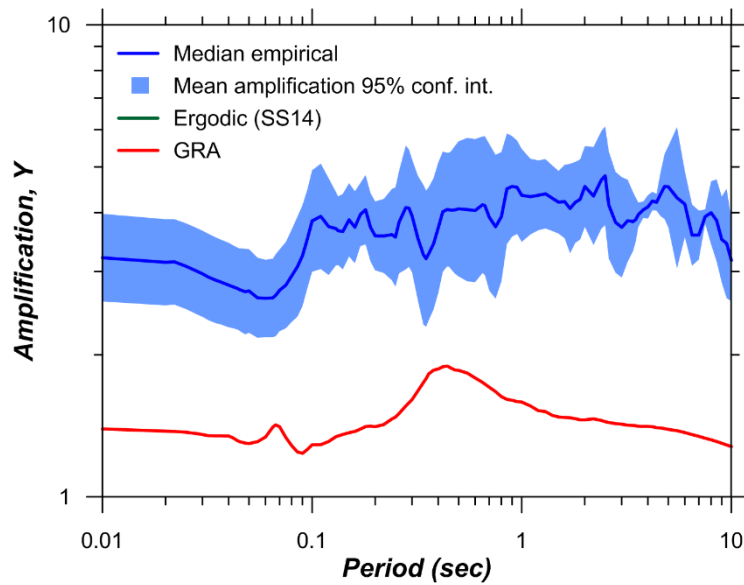
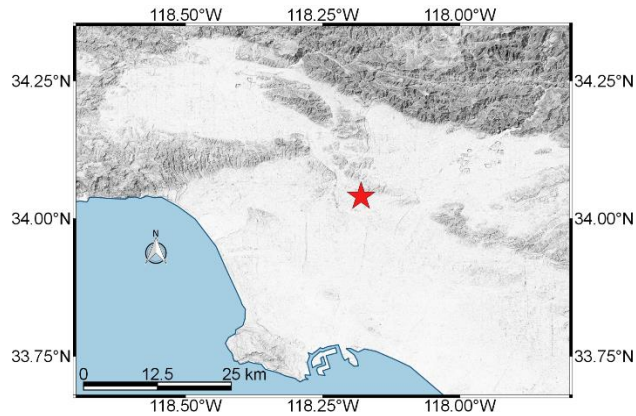
# Example Applications



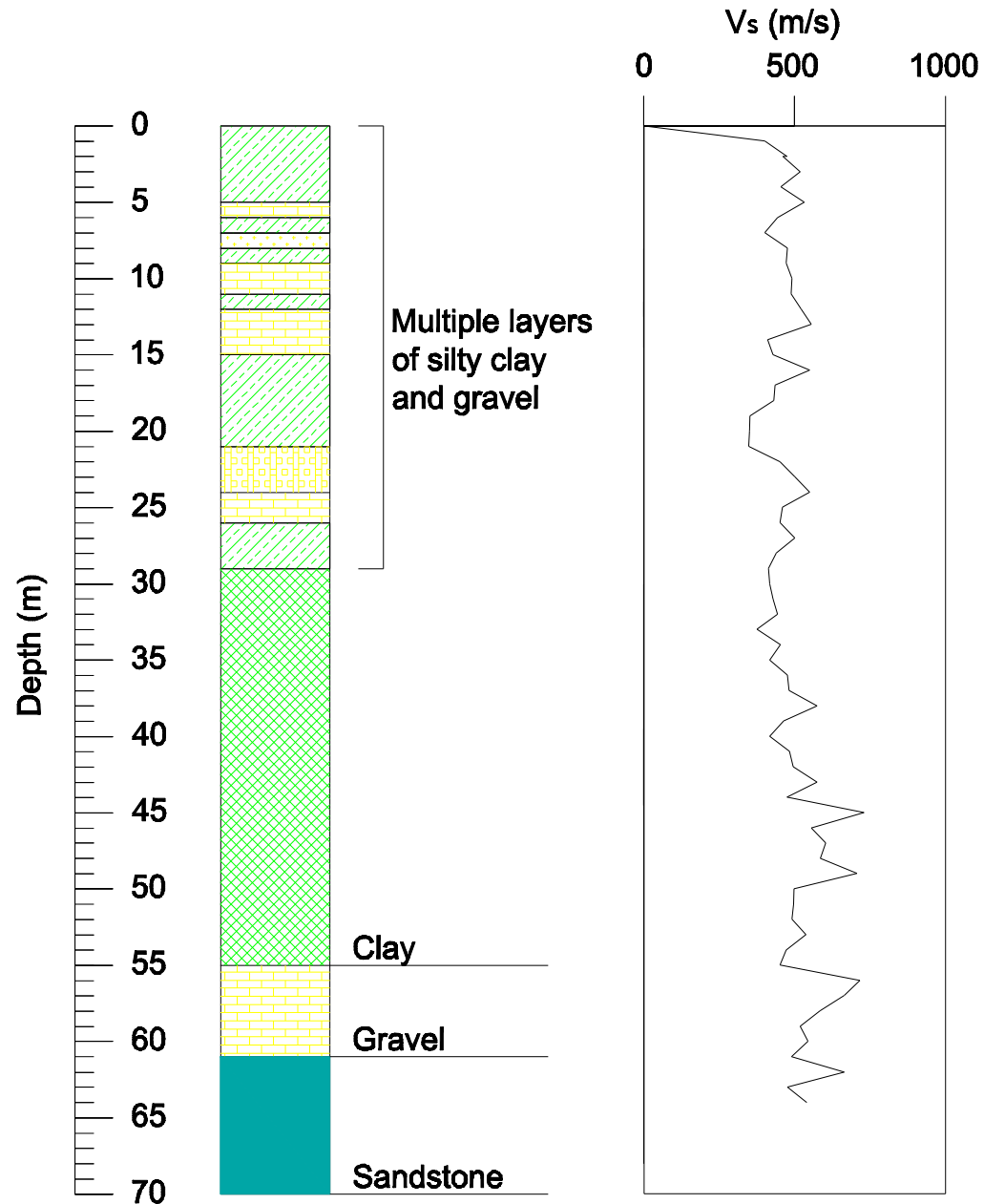
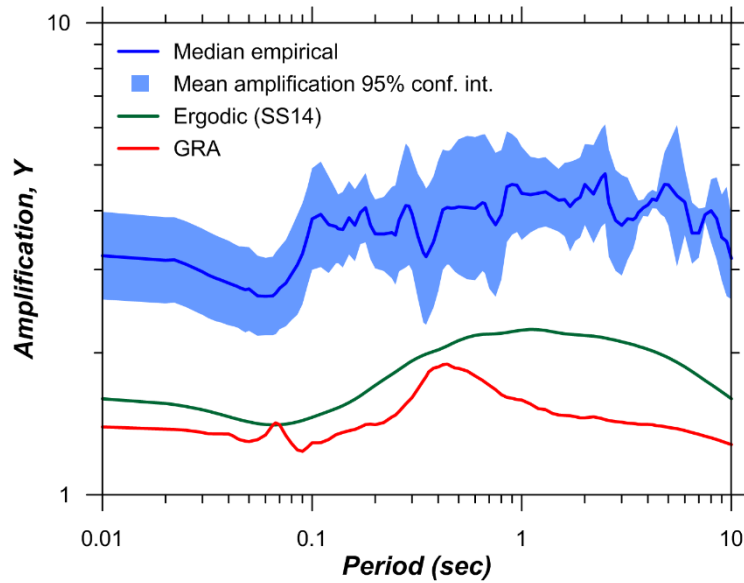
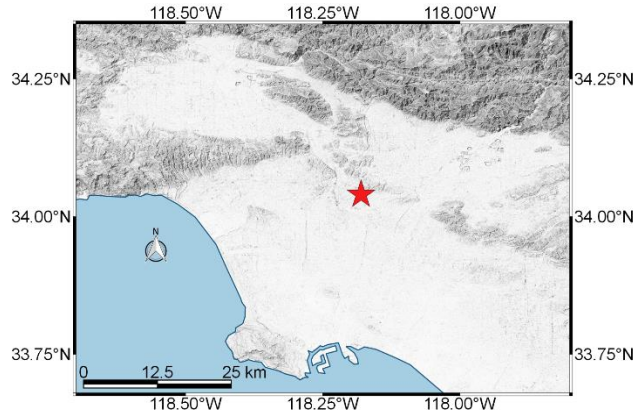
# Los Angeles – Obregon Park



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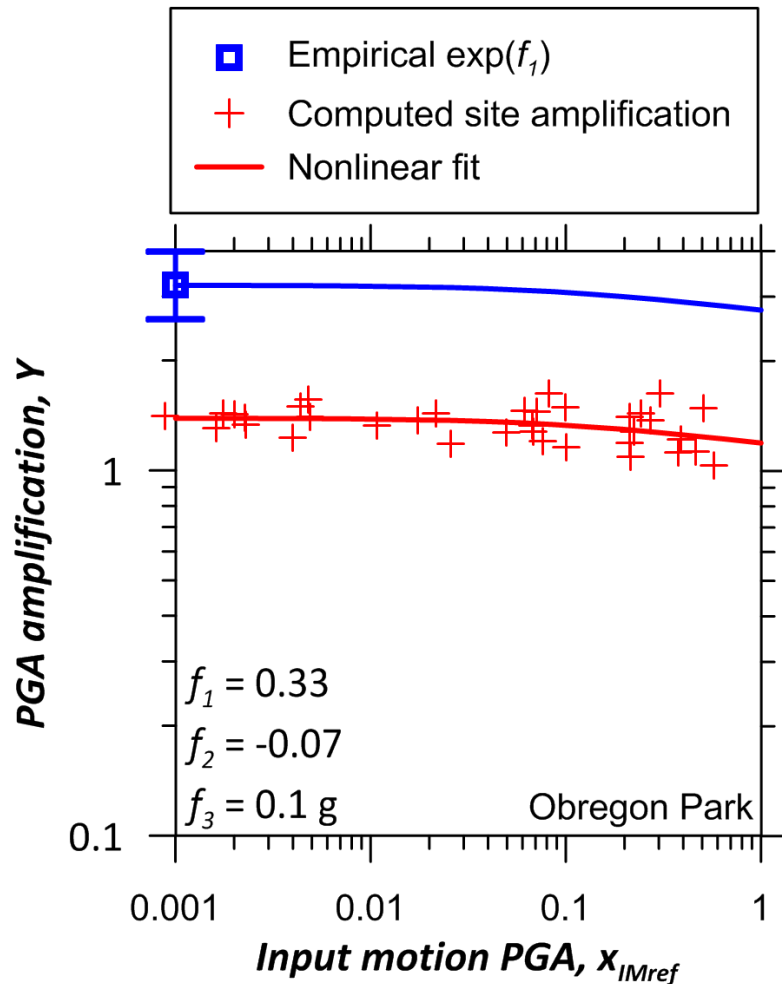


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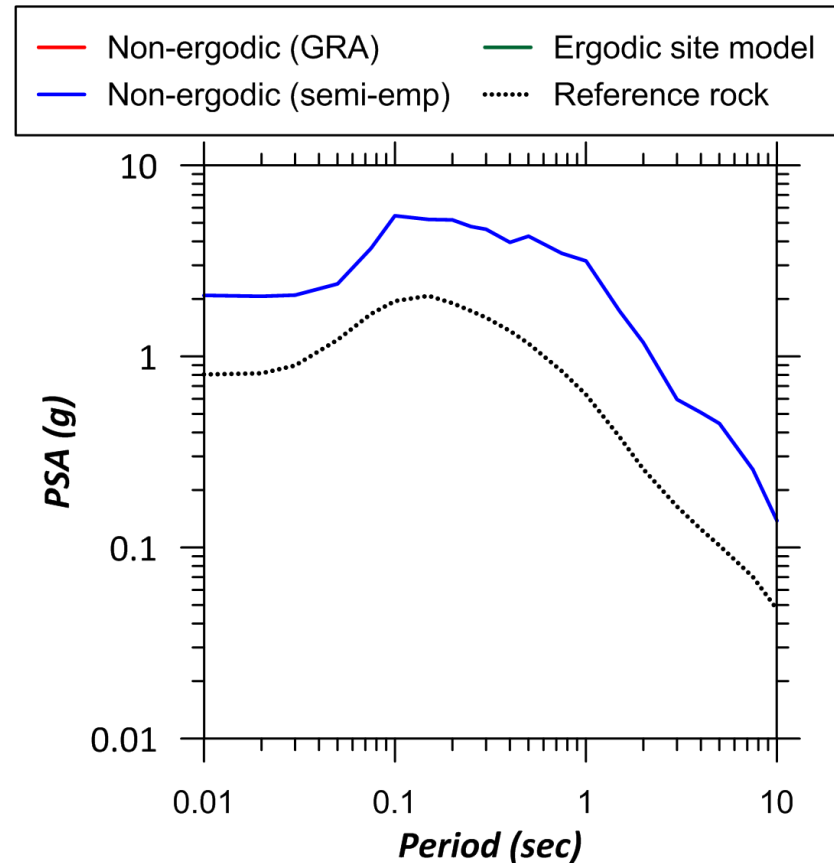


# Los Angeles – Obregon Park

Simulations for nonlinear parameters:

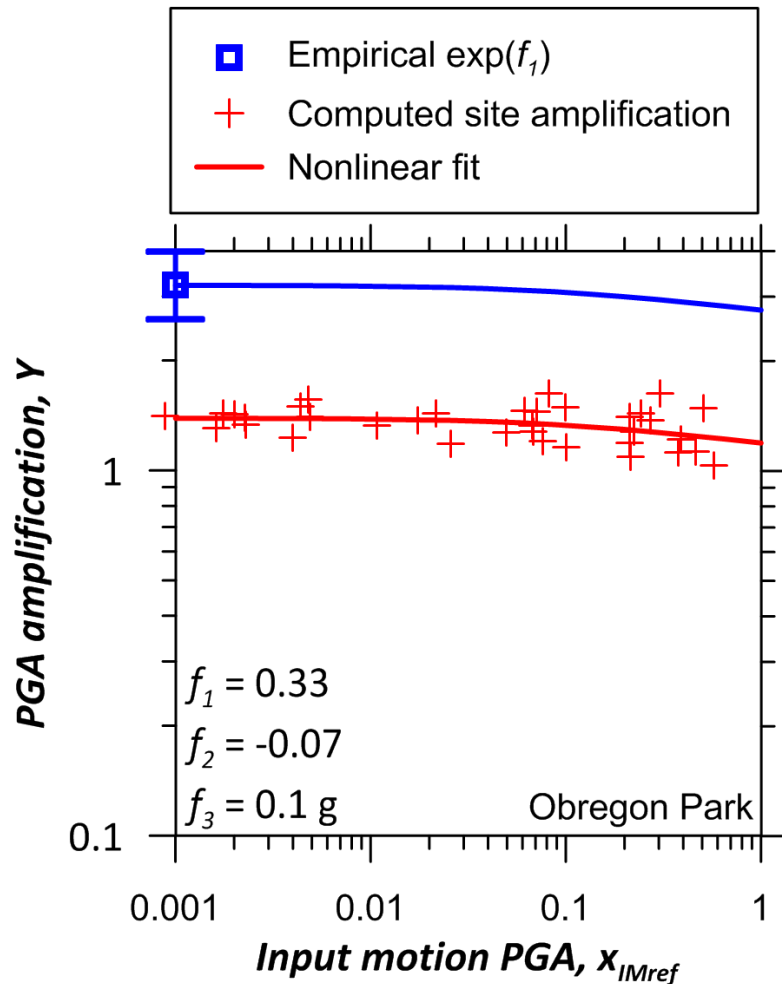


UHS: 2% Prob. exc. 50 yr

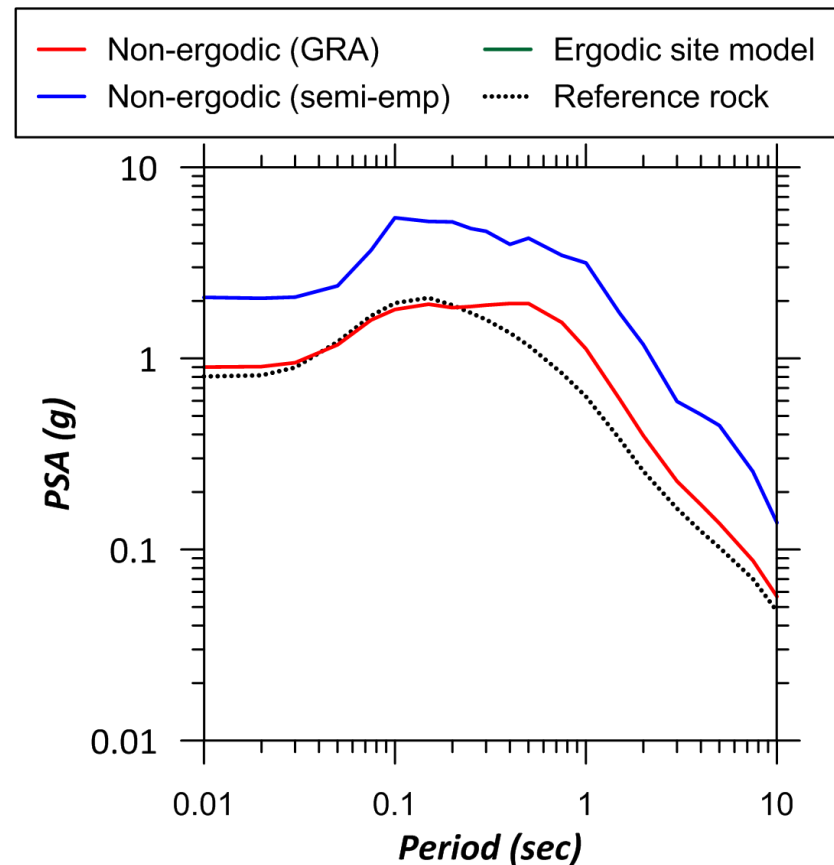


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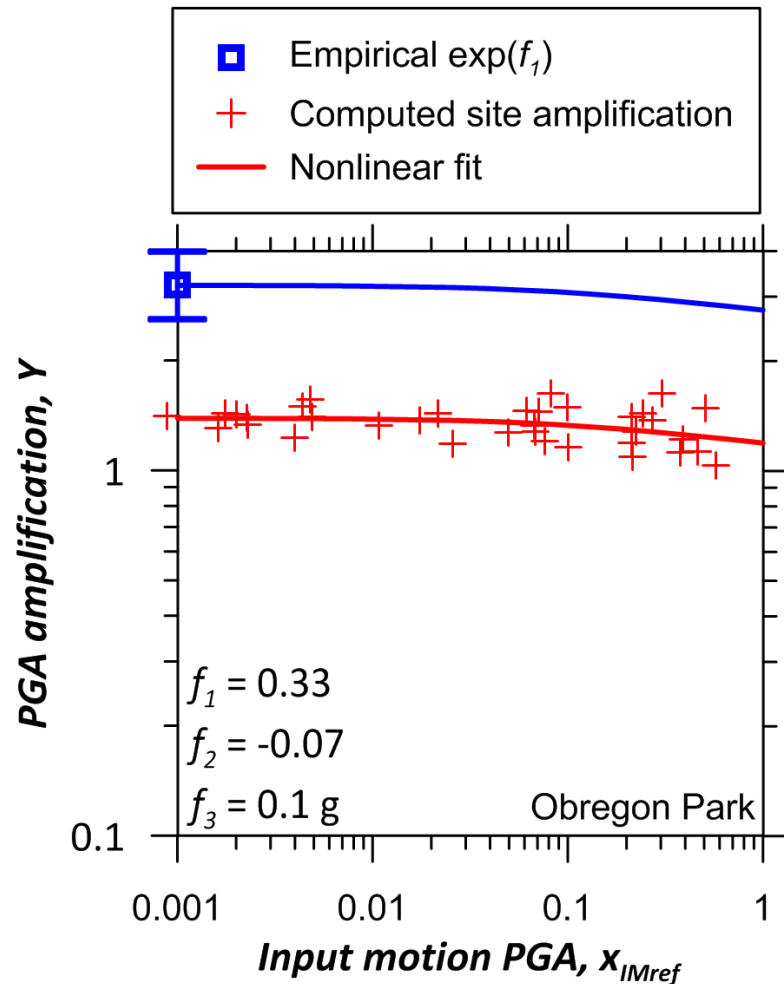


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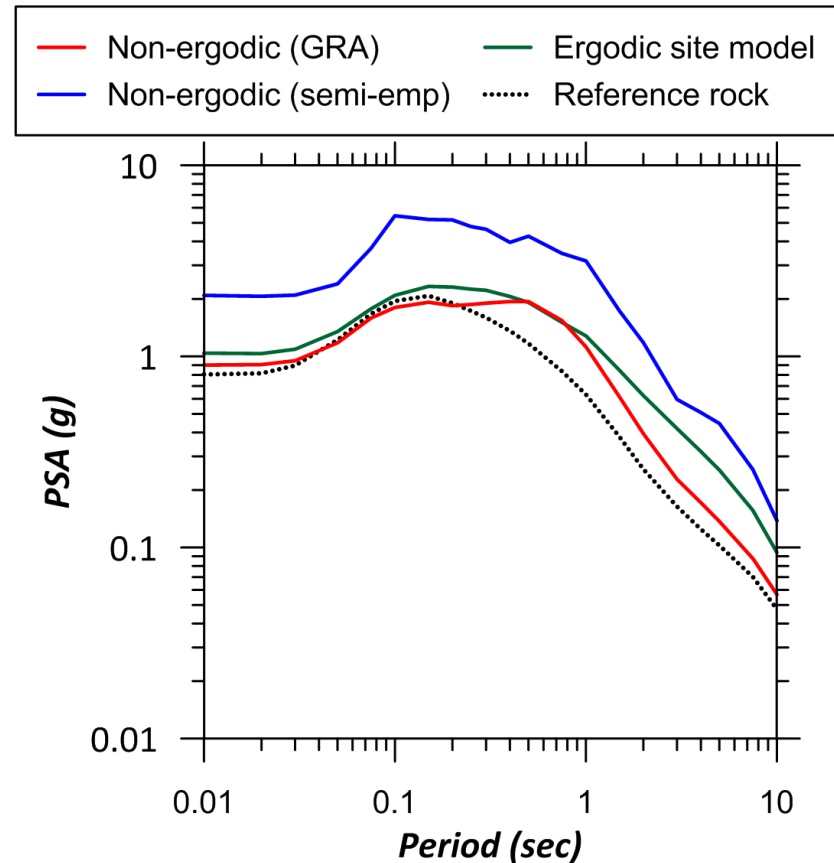


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Simulations for nonlinear parameters:



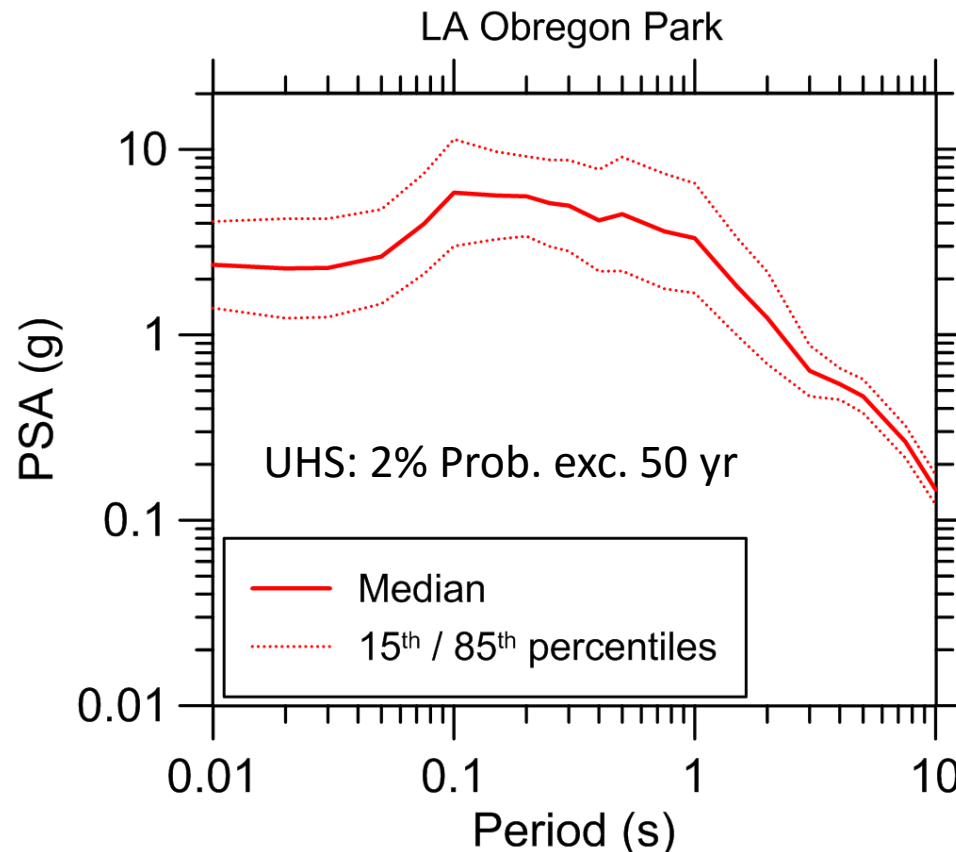
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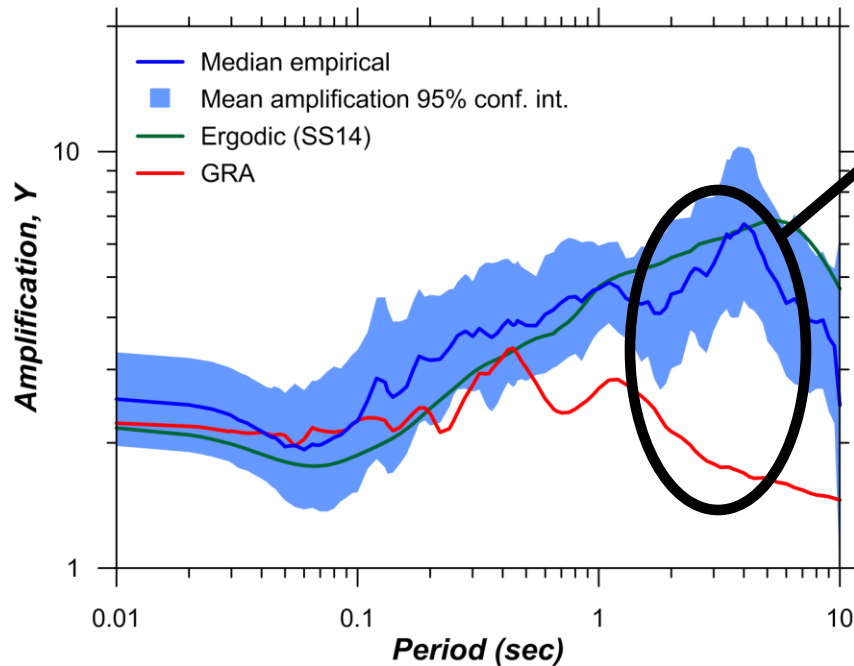
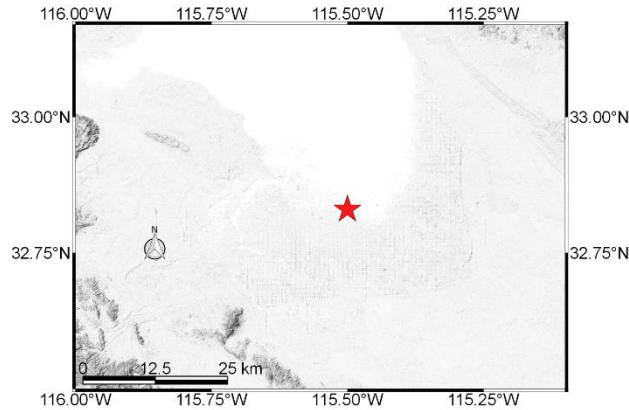
# Los Angeles – Obregon Park

Epistemic uncertainties in hazard from:

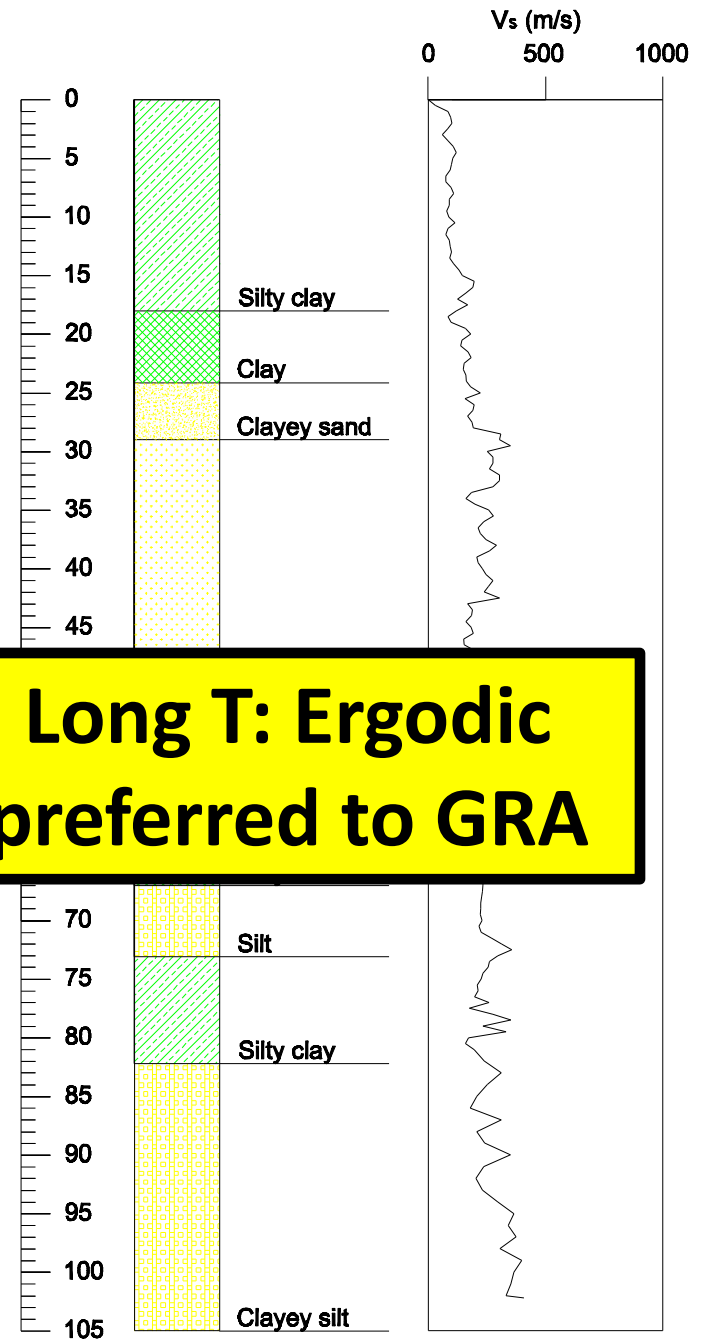
1. Uncertain semi-empirical mean hazard  $\mu_{\ln Y} \pm se_{\ln Y}$
2. Alternate  $\phi_{\ln Z}$  models



# El Centro Array #7



**Long T: Ergodic preferred to GRA**

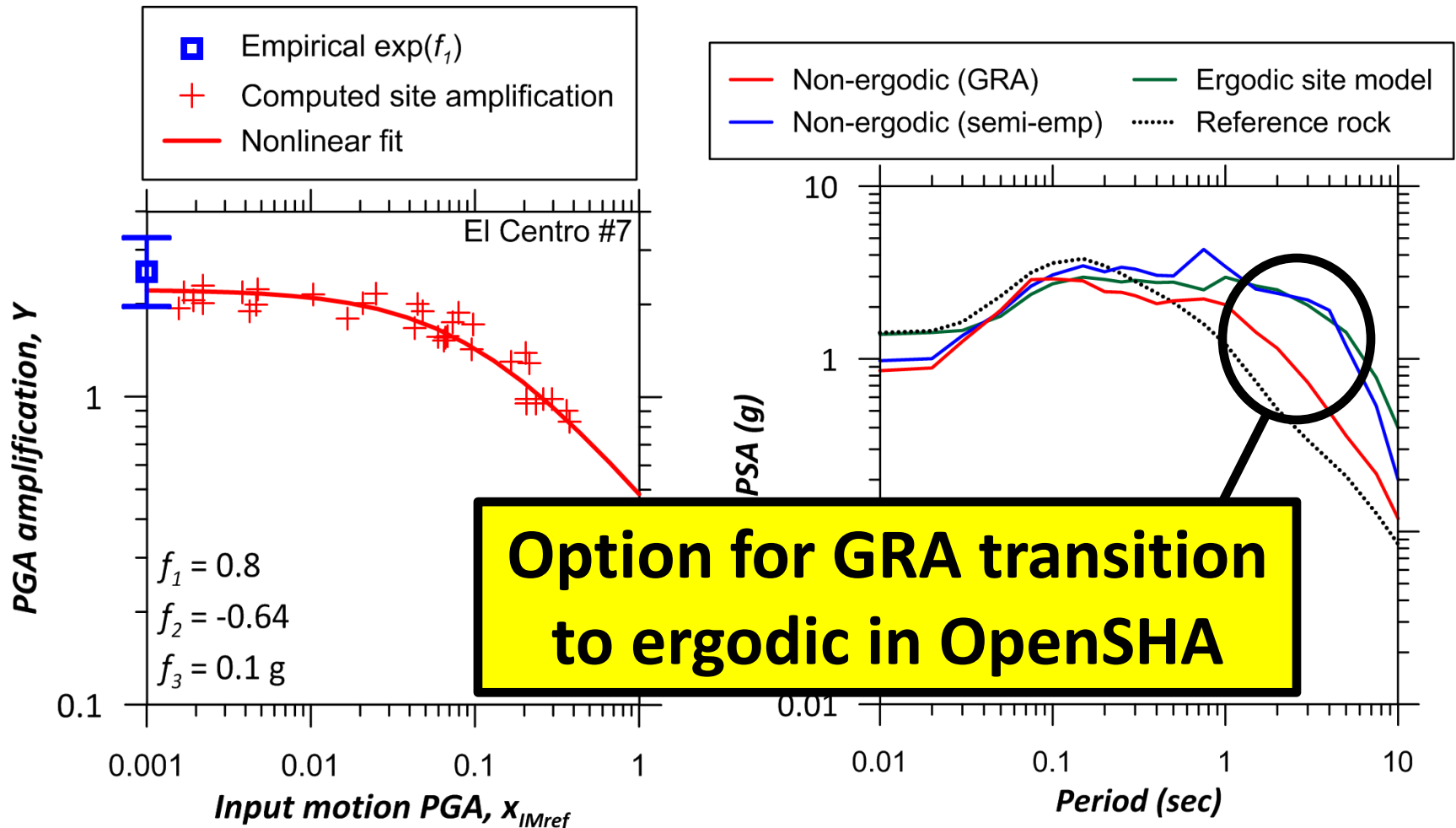




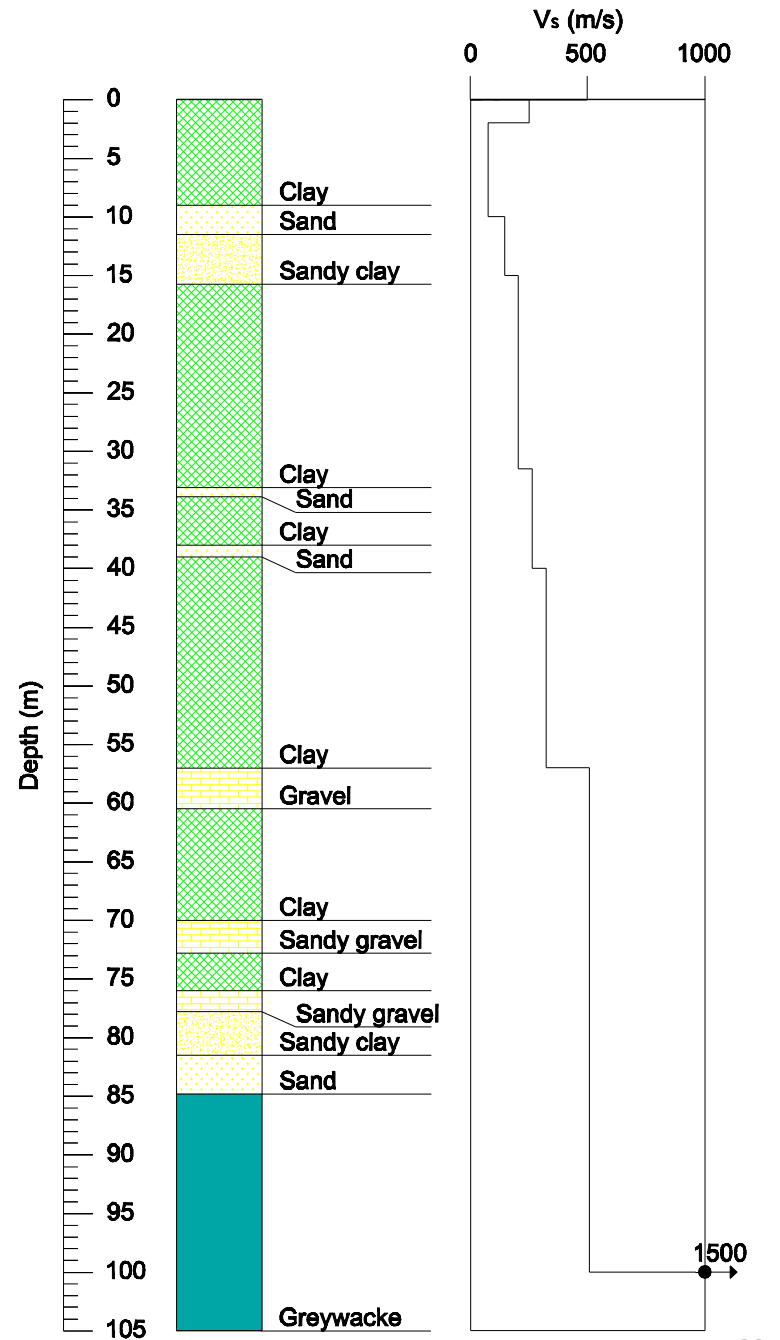
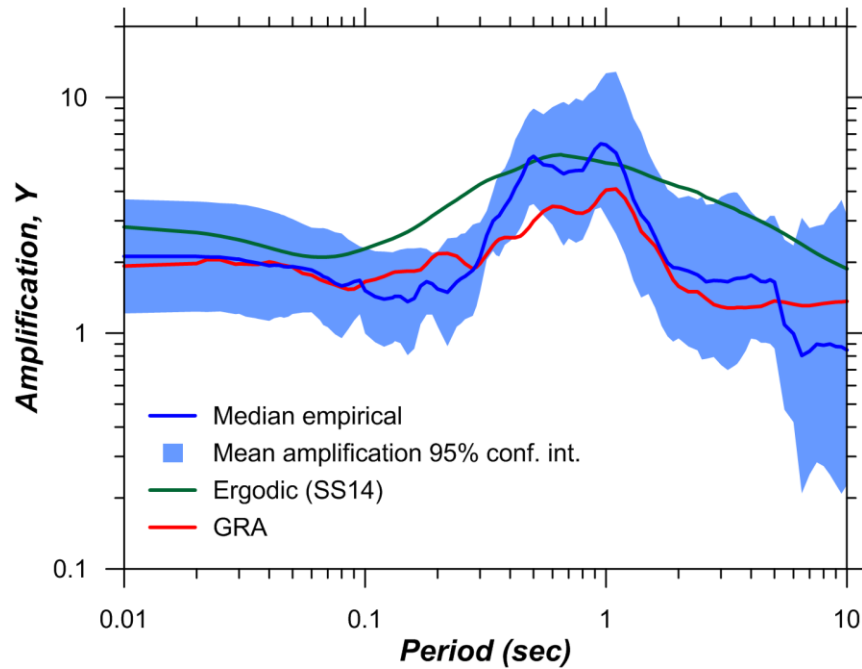
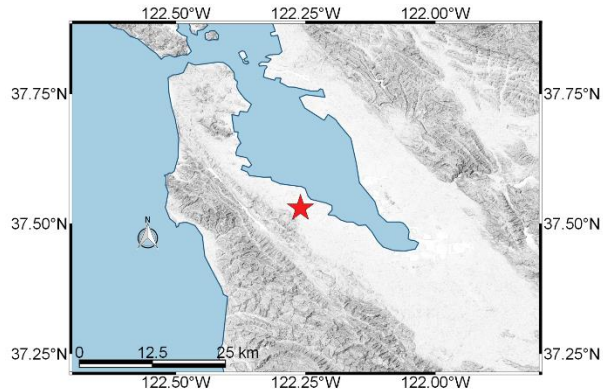
# El Centro Array #7

Simulations for nonlinear parameters:

UHS: 2% Prob. exc. 50 yr

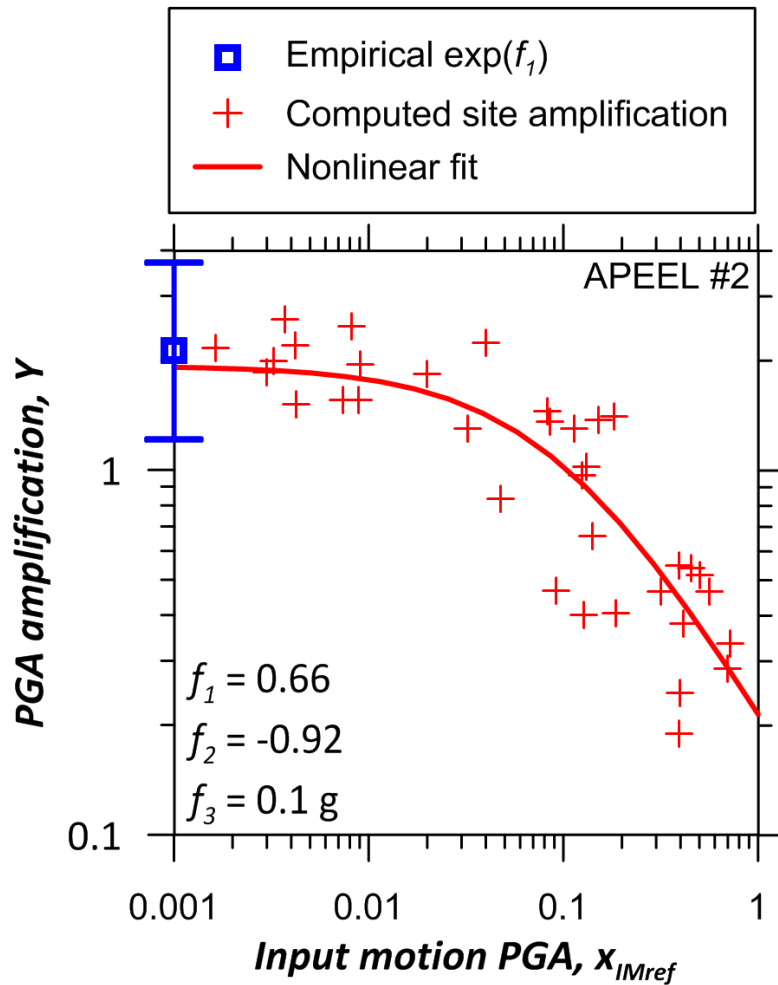


# Apeel #2

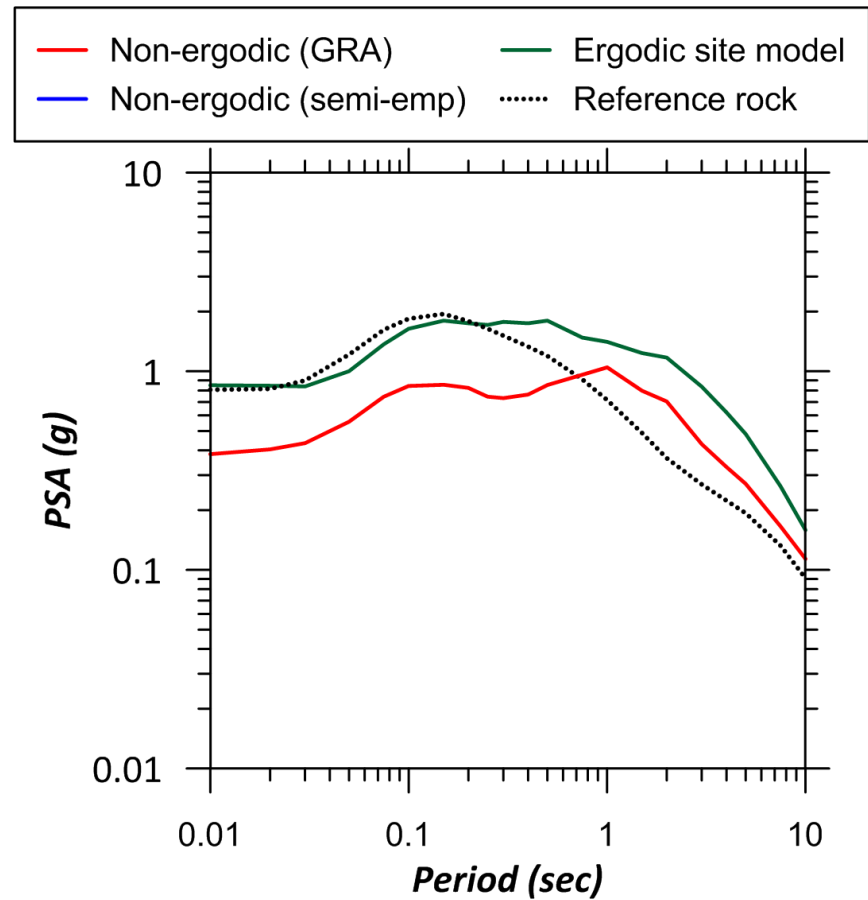


## Apeel #2

Simulations for nonlinear parameters:

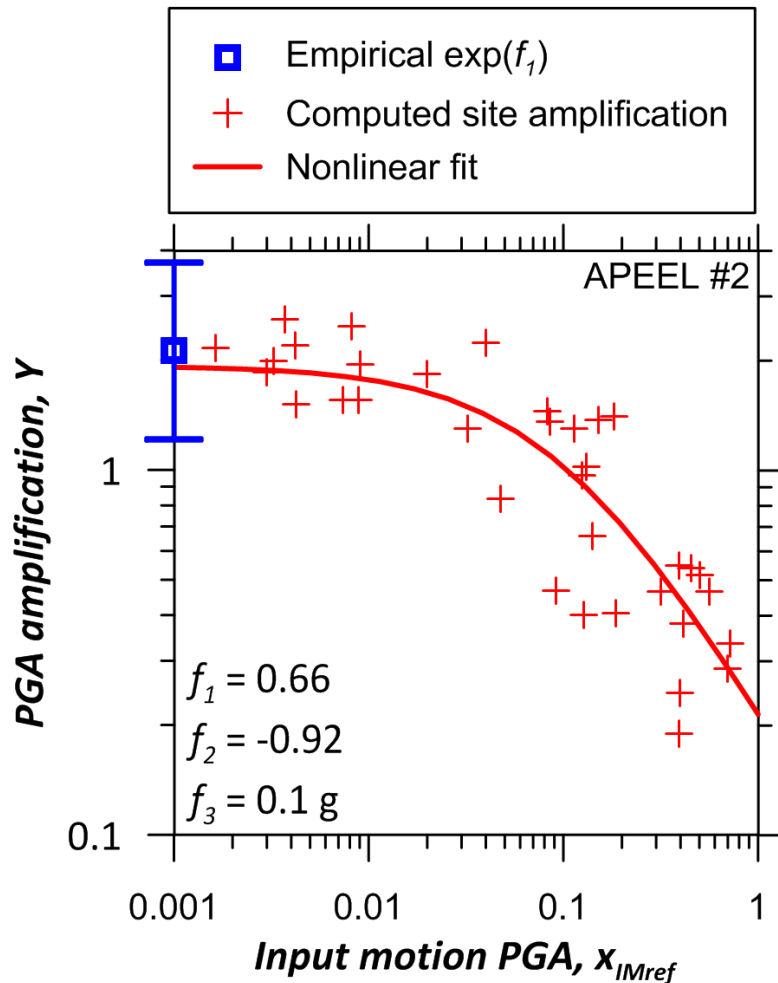


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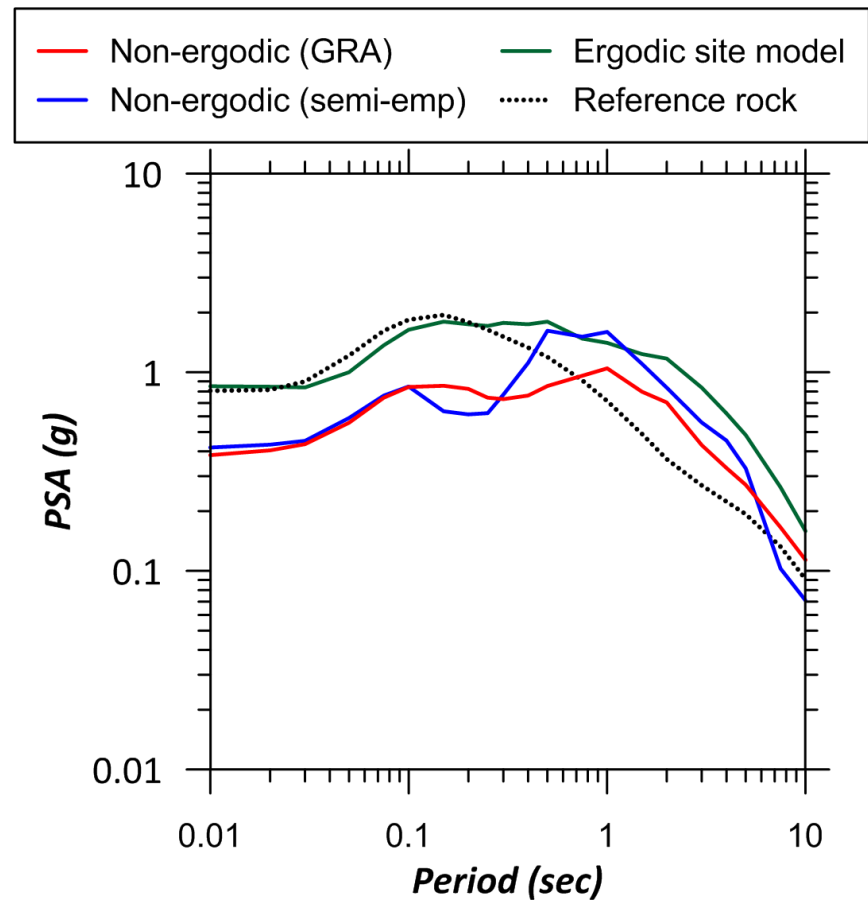


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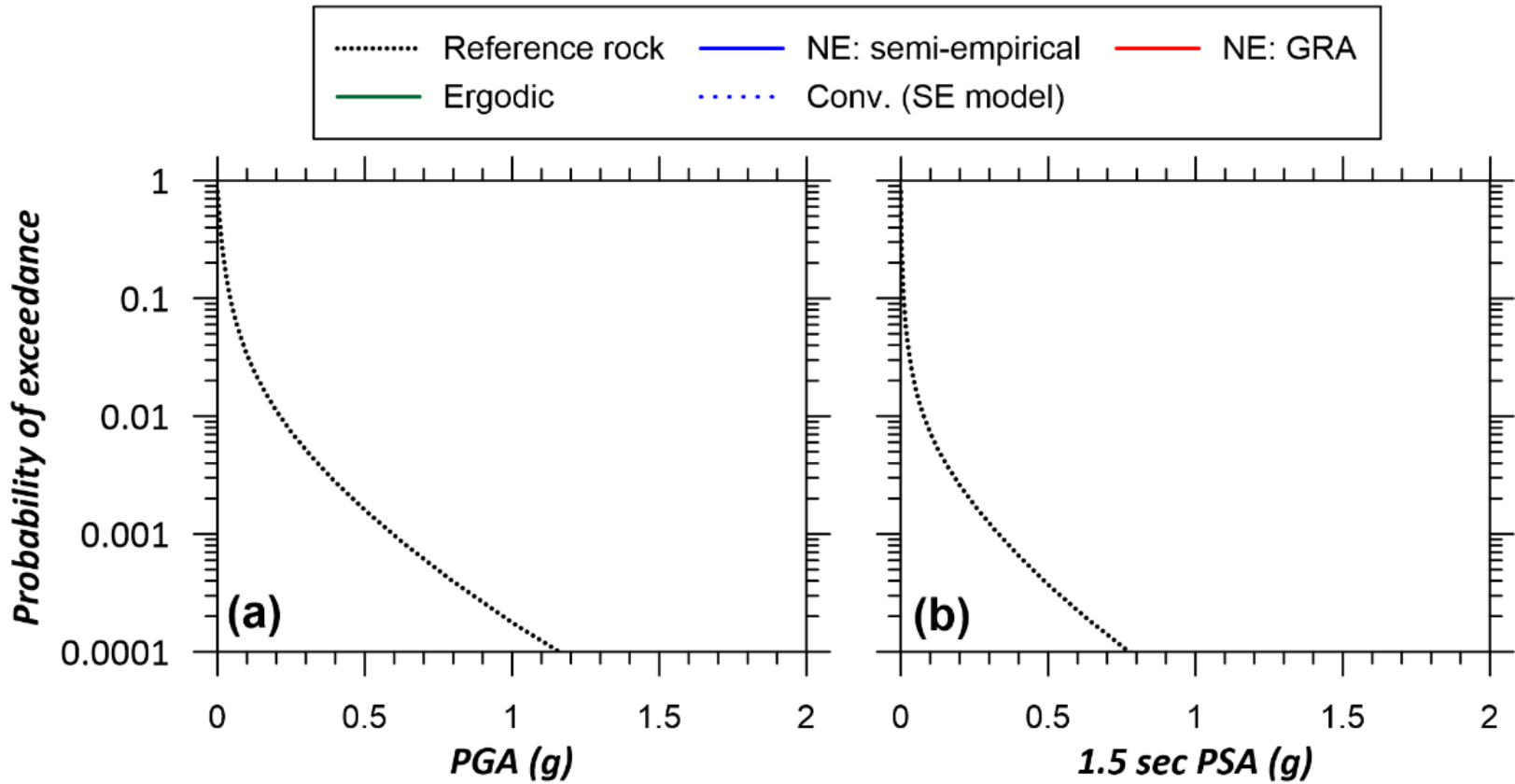
Simulations for nonlinear parameters:



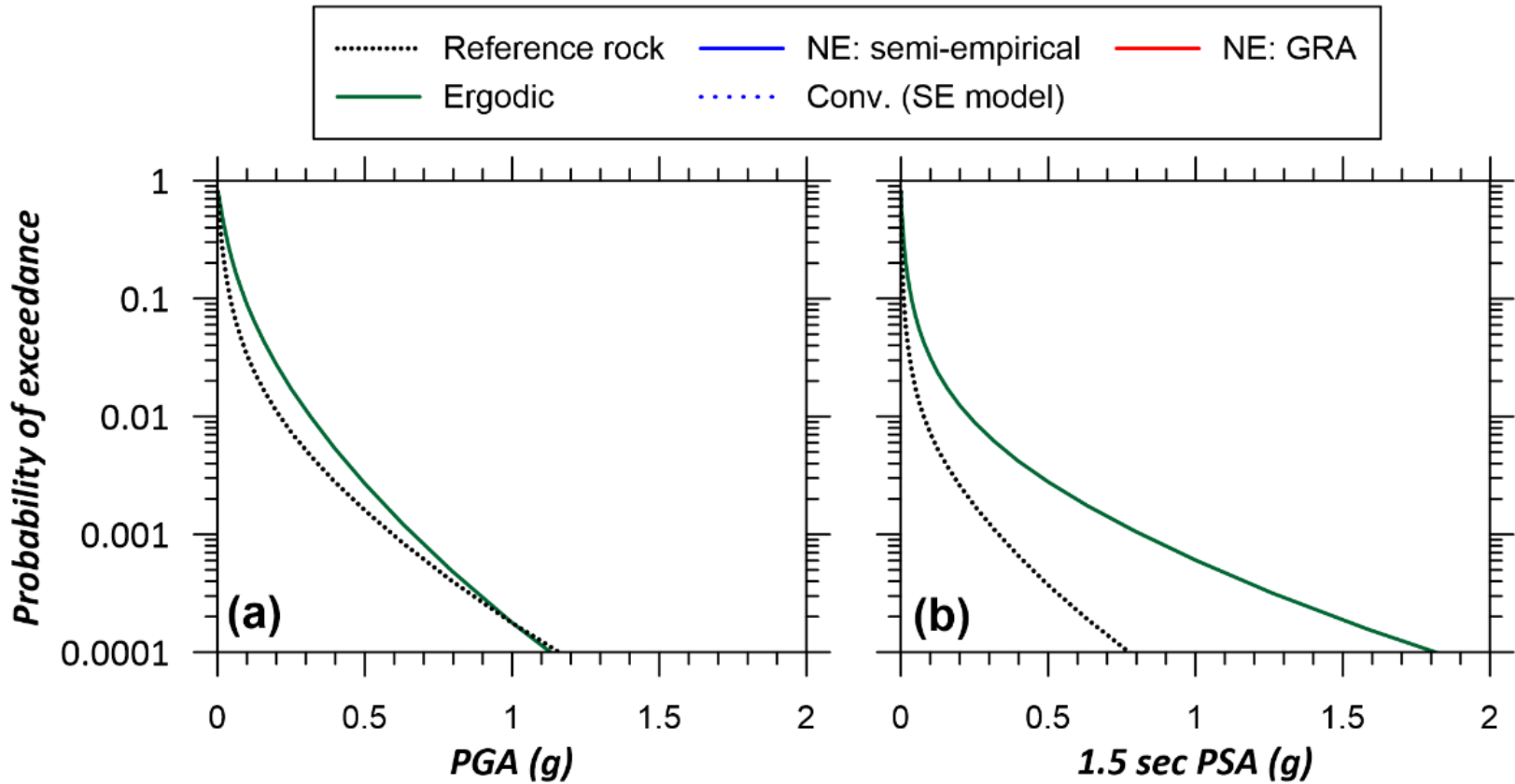
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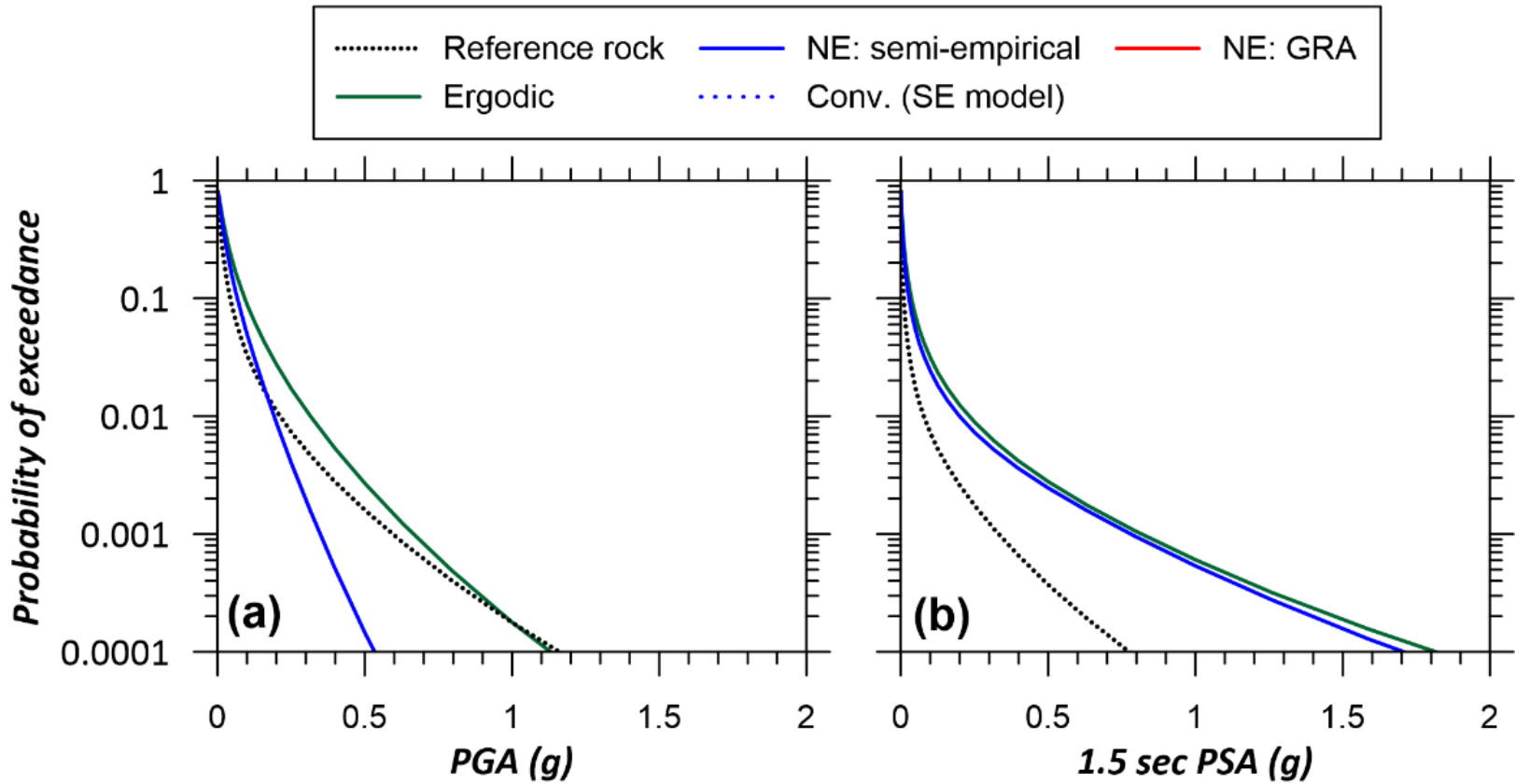
## Apeel #2: Hazard Curves



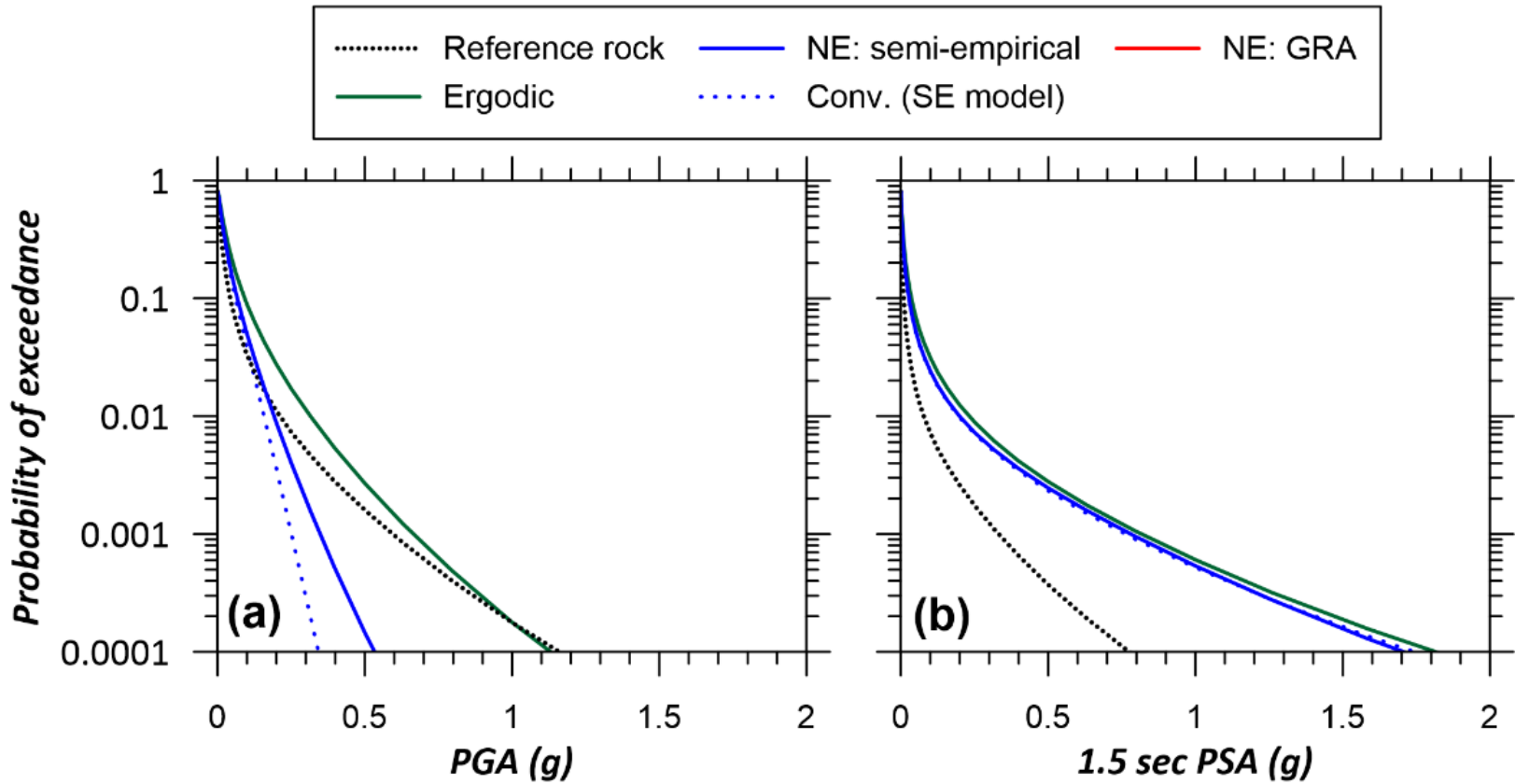
## Apeel #2: Hazard Curves



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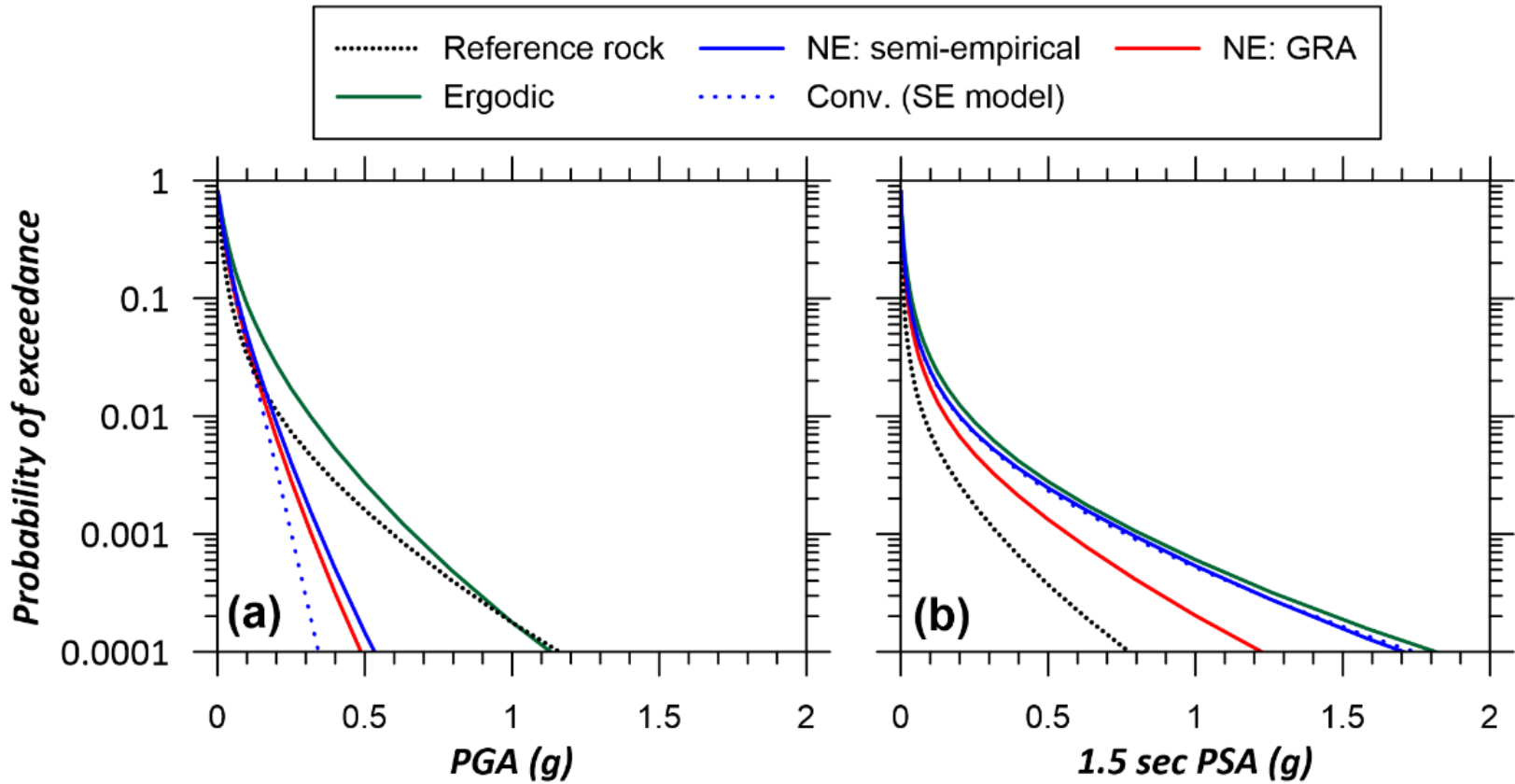


## Apeel #2: Hazard Curves





## Apeel #2: Hazard Curves



# Summary

- Ergodic (global) models easy to use, but sacrifice:
  - Precision. Loss of site-specific features.
  - Dispersion. Site-to-site variability must be included in hazard analysis.

# Summary

- Non-ergodic amplification preferred
  - Mean can capture site-specific features, such as site period
  - Lower  $\phi$  will tend to reduce hazard

# Summary

- Best applied as site-specific GMPE
  - Nonlinear effects accurately modelled
  - Changes in  $\phi$  applied
  - Enabled by non-ergodic option in OpenSHA
- Most recent site-specific analyses for major projects use convolution

# Summary

- Use of on- or near-site recordings preferred for linear response (semi-empirical)
- GRA drawbacks:
  - Biased at long periods
  - Short-period accuracy depends on geologic complexity.

# Summary

- More knowledge → lowered aleatory variability. Most often will reduce hazard appreciably
- If hazard matters in our risk analyses, we should be adopting these practices

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